3.2 Binary Search Trees

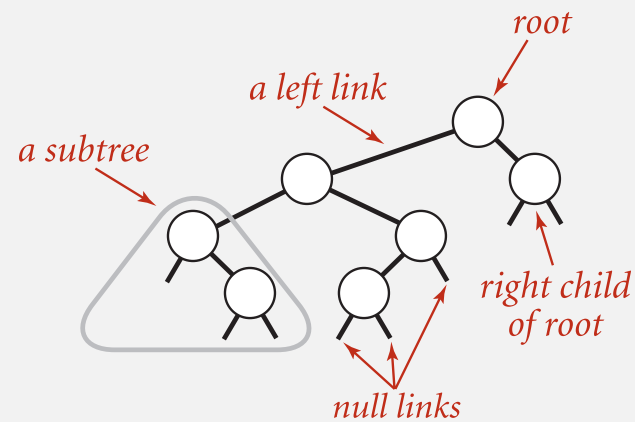
- BSTs
- ordered operations
- deletion

- BSTs
- ordered operations
- deletion

Definition. A BST is a binary tree in symmetric order.

A binary tree is either:

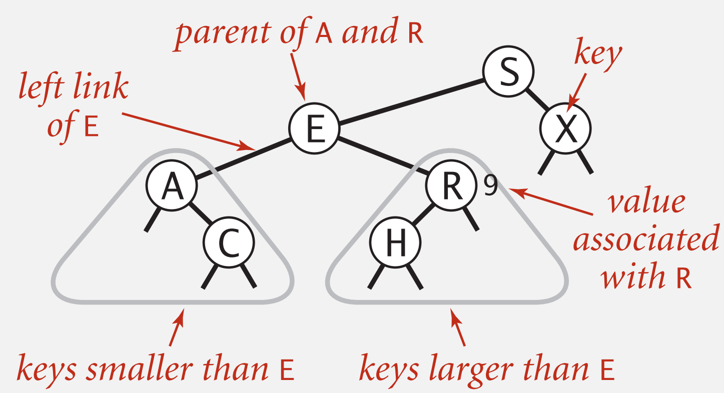
- Empty.
- Two disjoint binary trees (left and right).



Anatomy of a binary tree

Symmetric order. Each node has a key, and every node's key is:

- Larger than all keys in its left subtree.
- Smaller than all keys in its right subtree.



Anatomy of a binary search tree

BST representation in Java

Java definition. A BST is a reference to a root `Node`.

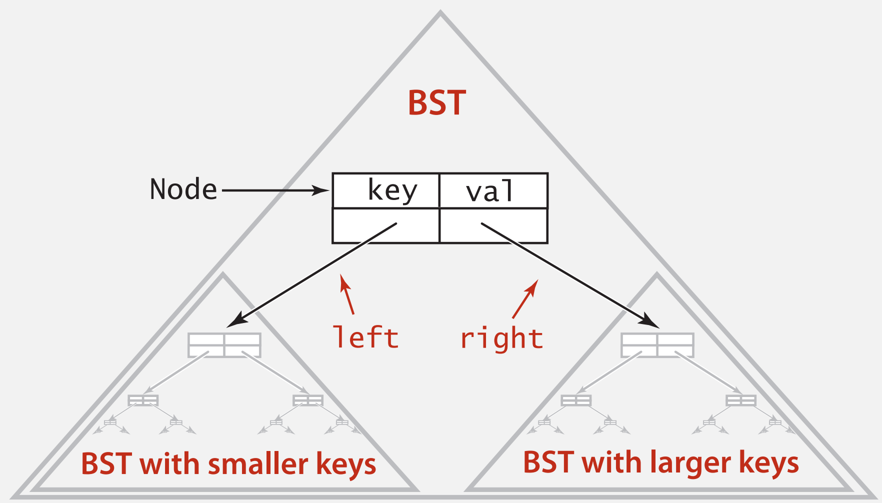
A `Node` is comprised of four fields:

- A `Key` and a `Value`.
- A reference to the left and right subtree.

smaller keys　　larger keys

```
private class Node
{
   private Key key;
   private Value val;
   private Node left, right;
   public Node(Key key, Value val)
   {
      this.key = key;
      this.val = val;
   }
}
```

`Key` and `Value` are generic types; `Key` is `Comparable`



Binary search tree

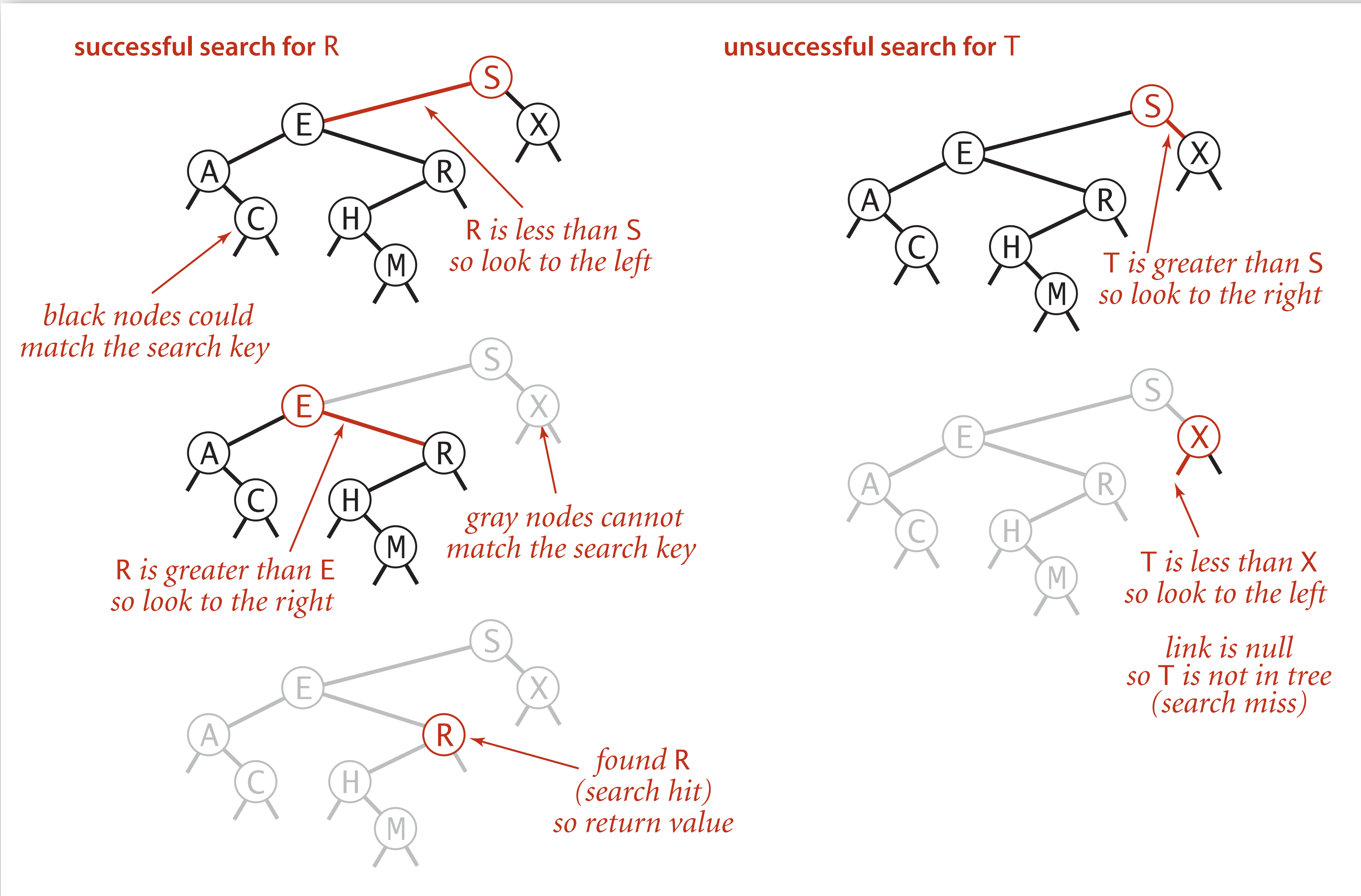
BST implementation (skeleton)

```
public class BST<Key extends Comparable<Key>, Value>
{
    private Node root;

   private class Node
   {  /* see previous slide */   }

   public void put(Key key, Value val)
   {  /* see next slides */   }

   public Value get(Key key)
   {  /* see next slides */   }

   public void delete(Key key)
   {  /* see next slides */   }

   public Iterable<Key> iterator()
   {  /* see next slides */   }

}
```

root of BST

BST search and insert demo

Get. Return value corresponding to given key, or `null` if no such key.



BST search: Java implementation

Get. Return value corresponding to given key, or `null` if no such key.

```
public Value get(Key key)
{
   Node x = root;
   while (x != null)
   {
      int cmp = key.compareTo(x.key);
      if      (cmp  < 0) x = x.left;
      else if (cmp  > 0) x = x.right;
      else if (cmp == 0) return x.val;
   }
   return null;
}
```

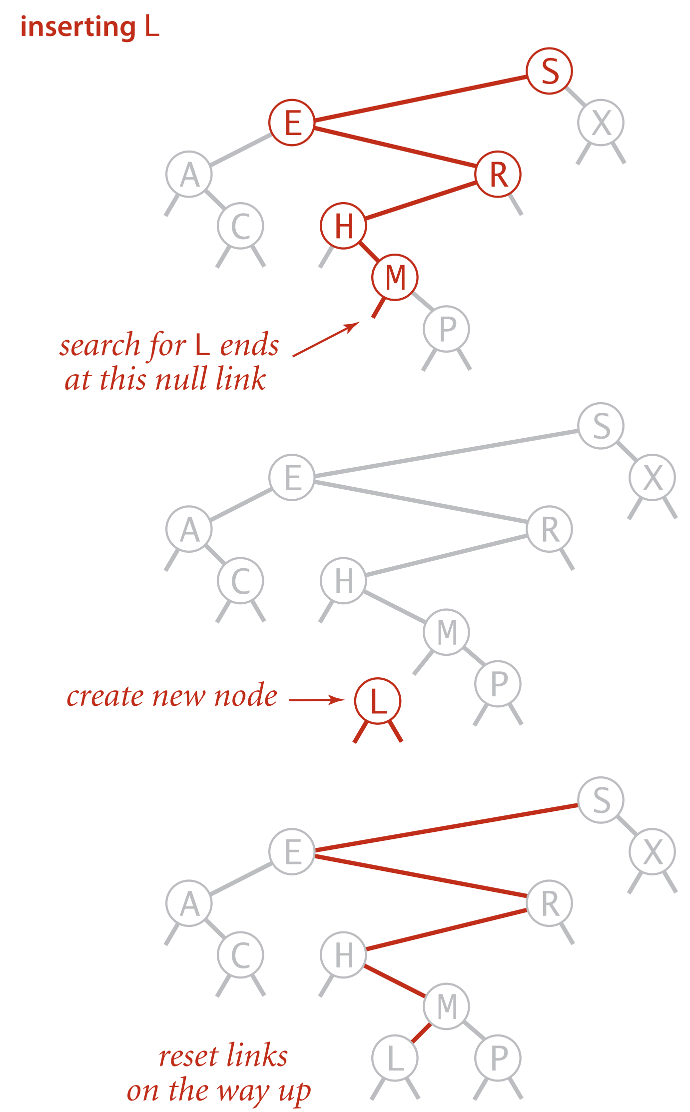
Cost. Number of compares is equal to 1 + depth of node.

BST insert

Put. Associate value with key.

Search for key, then two cases:

- Key in tree ⇒ reset value.
- Key not in tree ⇒ add new node.



Insertion into a BST

BST insert: Java implementation

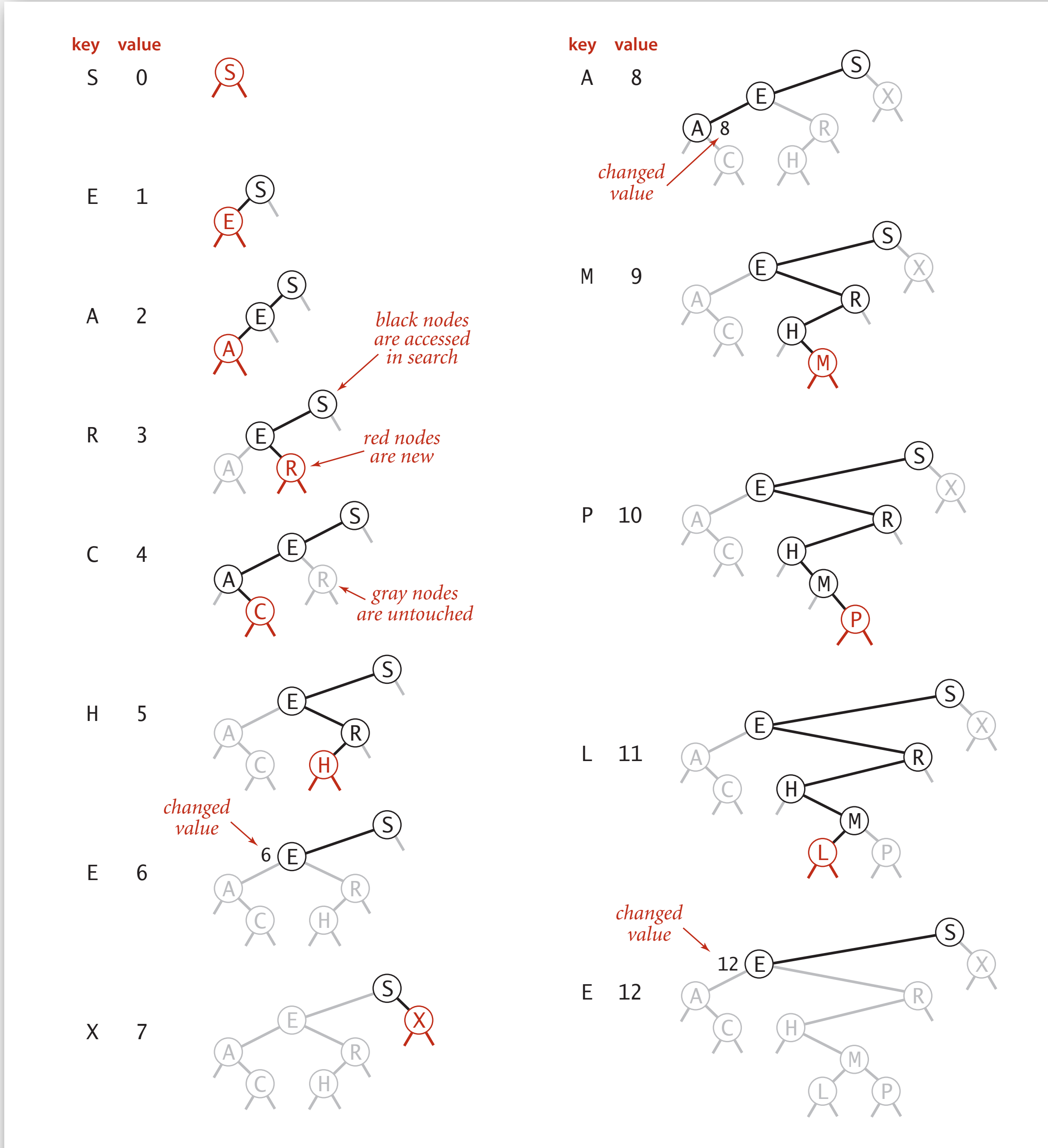
Put. Associate value with key.

concise, but tricky, recursive code; read carefully!

```
public void put(Key key, Value val)
{  root = put(root, key, val);  }

private Node put(Node x, Key key, Value val)
{
   if (x == null) return new Node(key, val);
   int cmp = key.compareTo(x.key);
   if      (cmp  < 0)
      x.left  = put(x.left,  key, val);
   else if (cmp  > 0)
      x.right = put(x.right, key, val);
   else if (cmp == 0)
      x.val = val;
   return x;
}
```

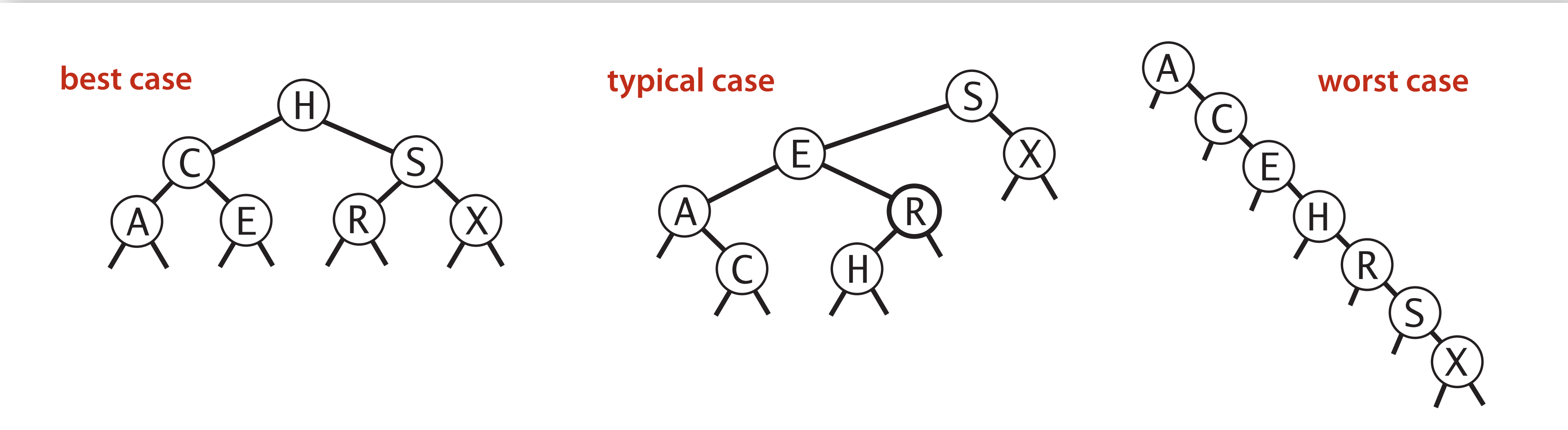
Cost. Number of compares is equal to 1 + depth of node.

BST trace: standard indexing client



Tree shape

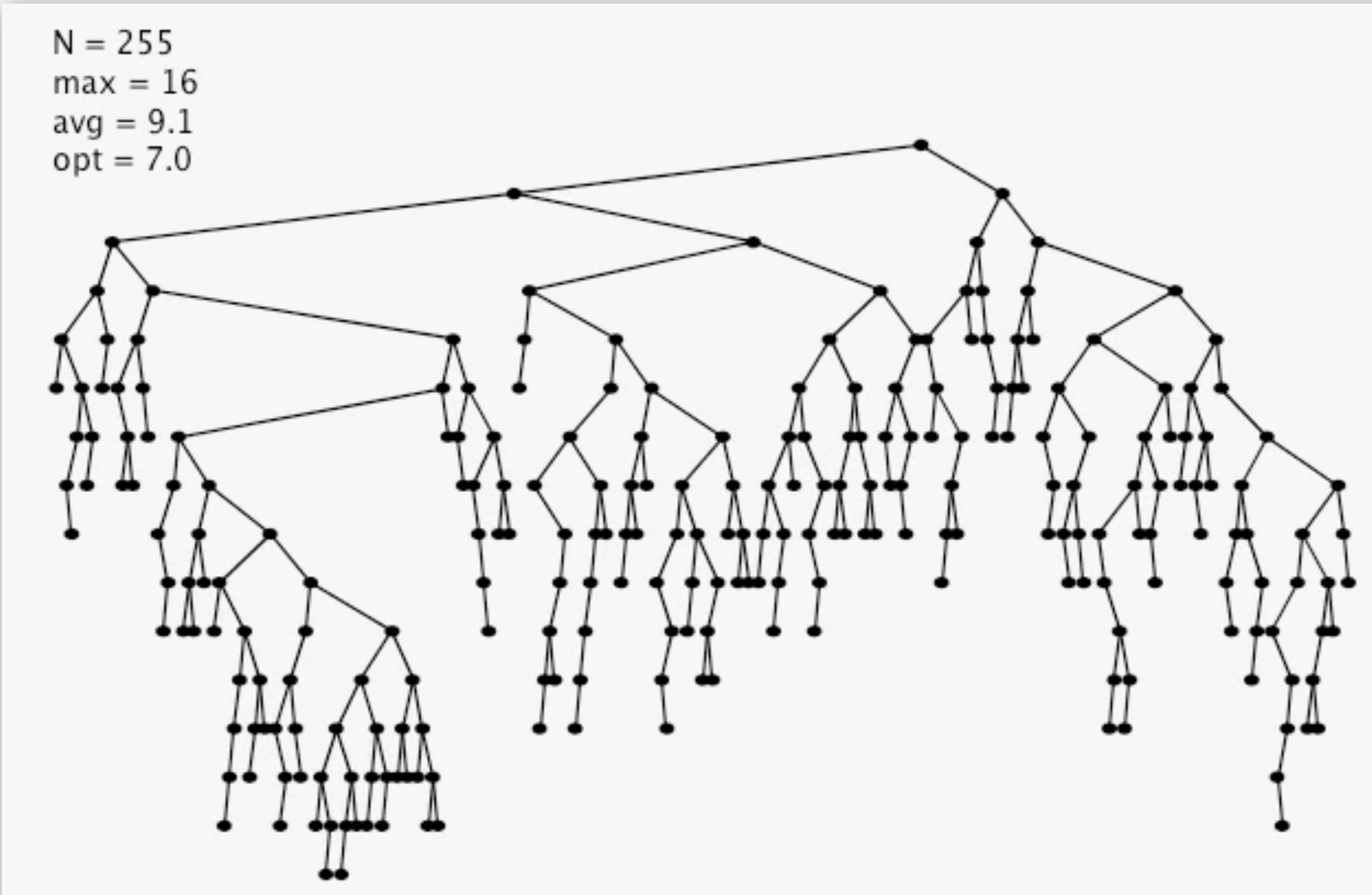
- Many BSTs correspond to same set of keys.
- Number of compares for search/insert is equal to 1 + depth of node.



Remark. Tree shape depends on order of insertion.

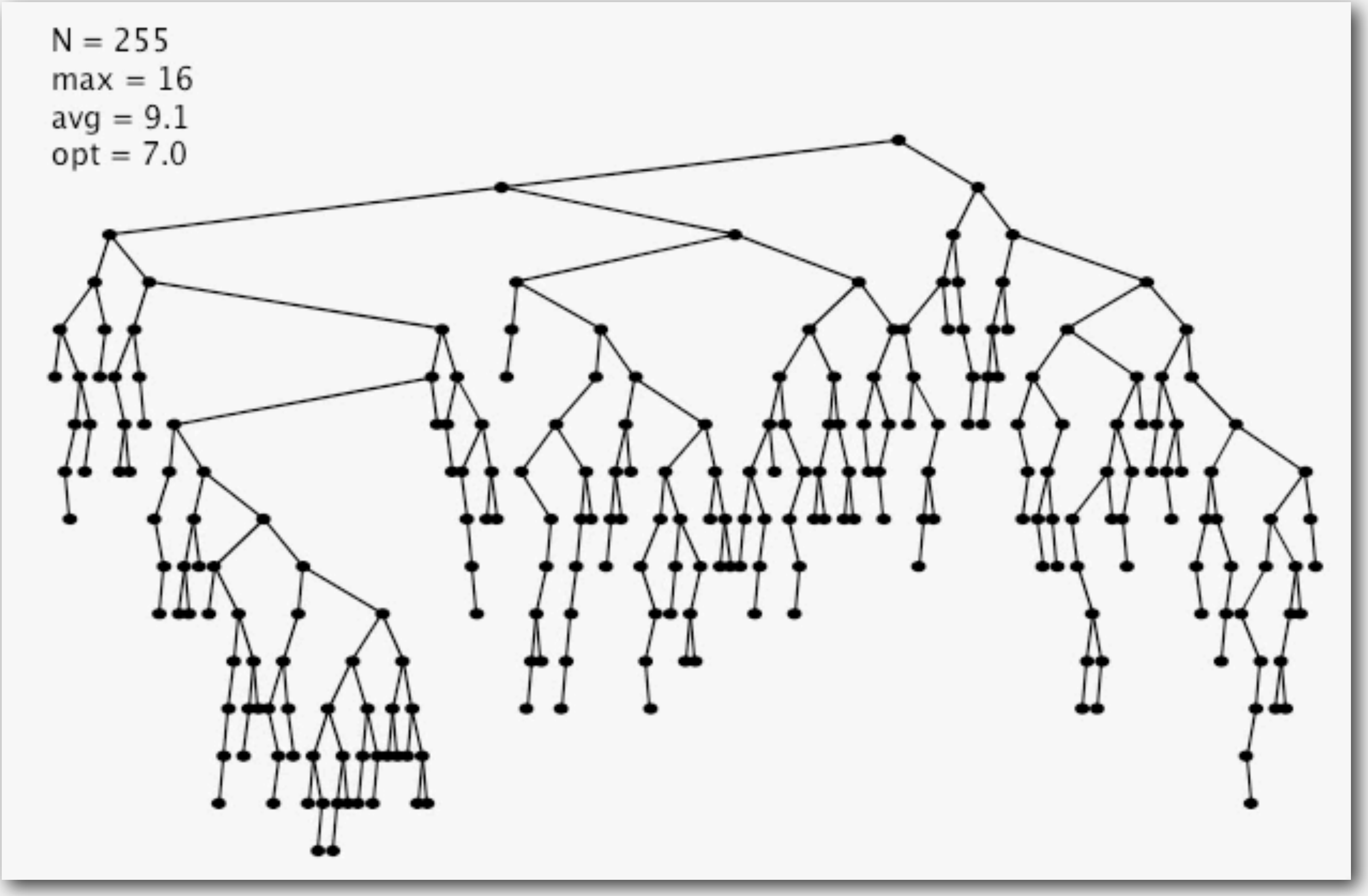
BST insertion: random order

Observation. If keys inserted in random order, tree stays relatively flat.

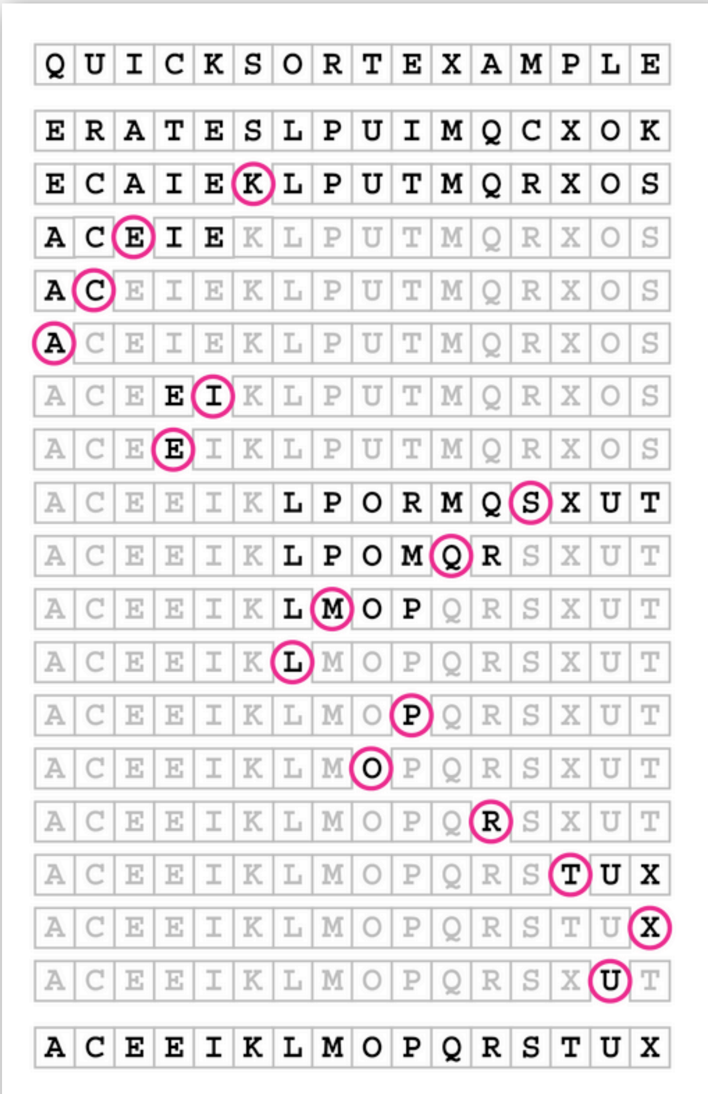


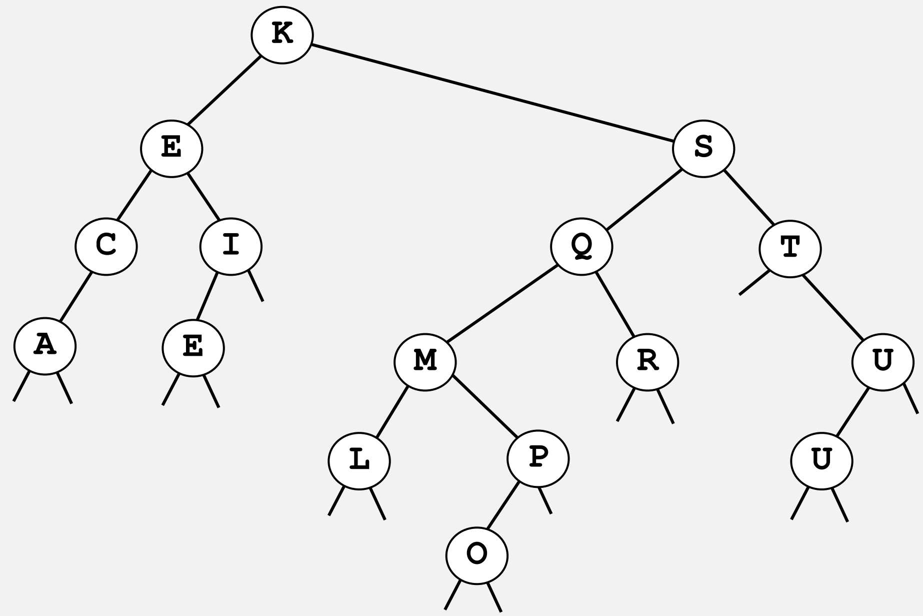
BST insertion: random order visualization

Ex. Insert keys in random order.



Correspondence between BSTs and quicksort partitioning





Remark. Correspondence is 1-1 if array has no duplicate keys.

Proposition. If keys are inserted in random order, the expected number of compares for a search/insert is $\sim 2 \ln N$.

Pf. 1-1 correspondence with quicksort partitioning.

Proposition. [Reed, 2003] If keys are inserted in random order, expected height of tree is $\sim 4.311 \ln N$.

But… Worst-case height is N.
(exponentially small chance when keys are inserted in random order)

ST implementations: summary

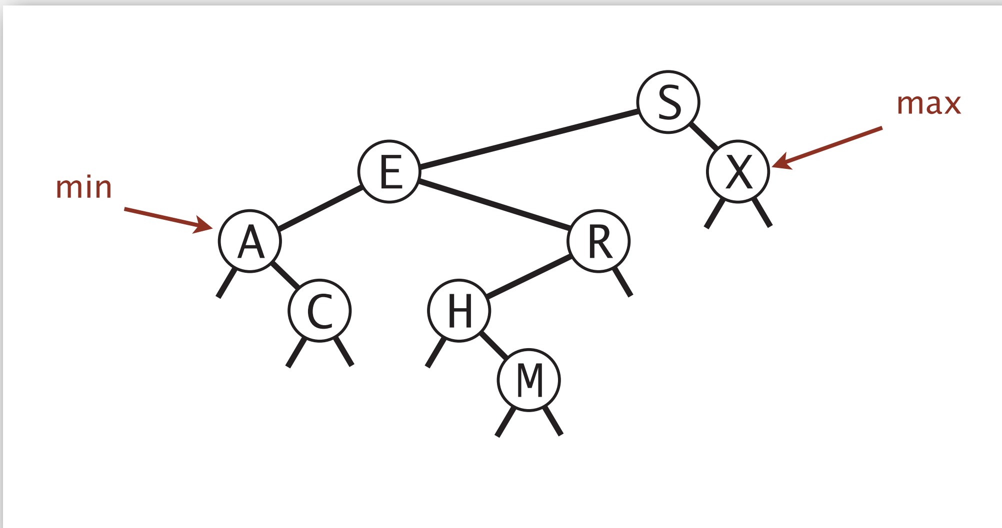
implementation	guarantee		average case		ordered ops?	operations on keys
	search	insert	search hit	insert		
sequential search (unordered list)	N	N	N/2	N	no	`equals()`
binary search (ordered array)	lg N	N	lg N	N/2	yes	`compareTo()`
BST	N	N	1.39 lg N	1.39 lg N	?	`compareTo()`

- BSTs
- **ordered operations**
- deletion

Minimum and maximum

Minimum. Smallest key in table.

Maximum. Largest key in table.

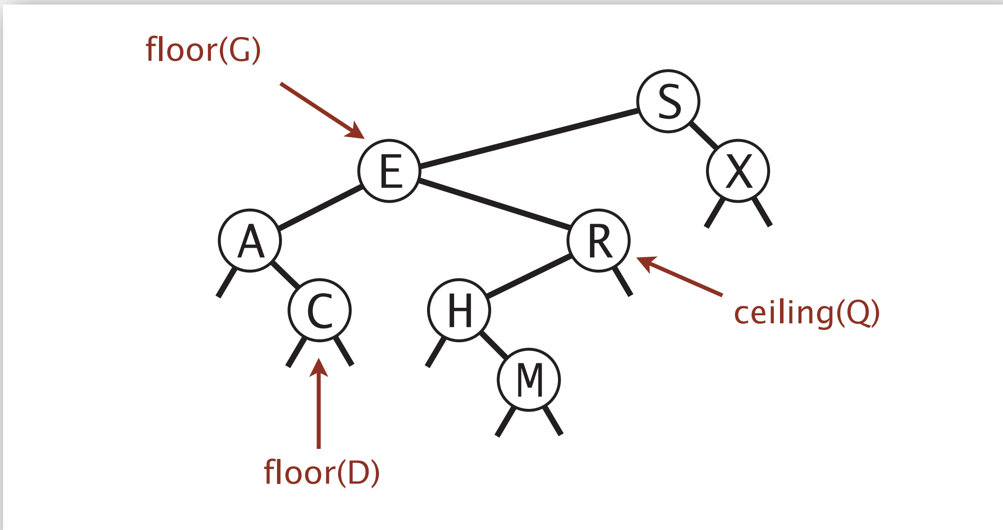


Q. How to find the min / max?

Floor and ceiling

Floor. Largest key ≤ to a given key.

Ceiling. Smallest key ≥ to a given key.



Q. How to find the floor /ceiling?

Computing the floor

Case 1. [k equals the key at root]

The floor of k is k.

Case 2. [k is less than the key at root]

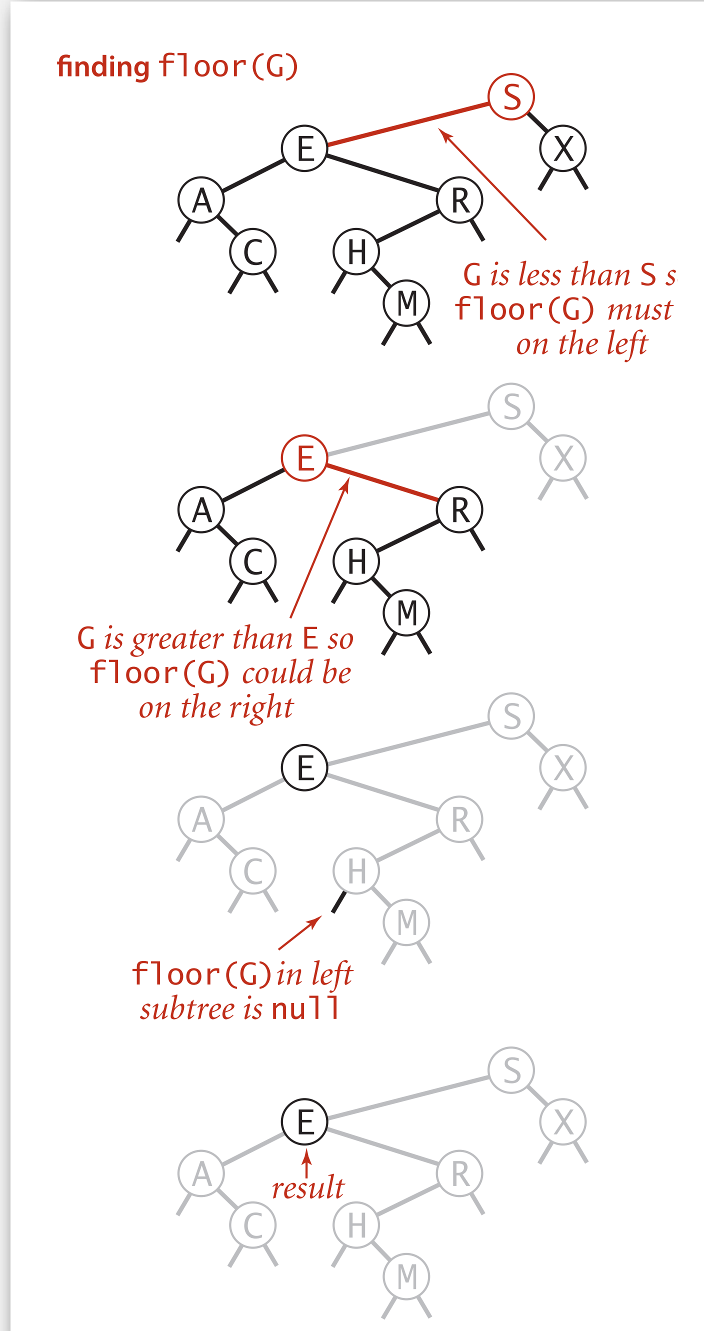
The floor of k is in the left subtree.

Case 3. [k is greater than the key at root]

The floor of k is in the right subtree

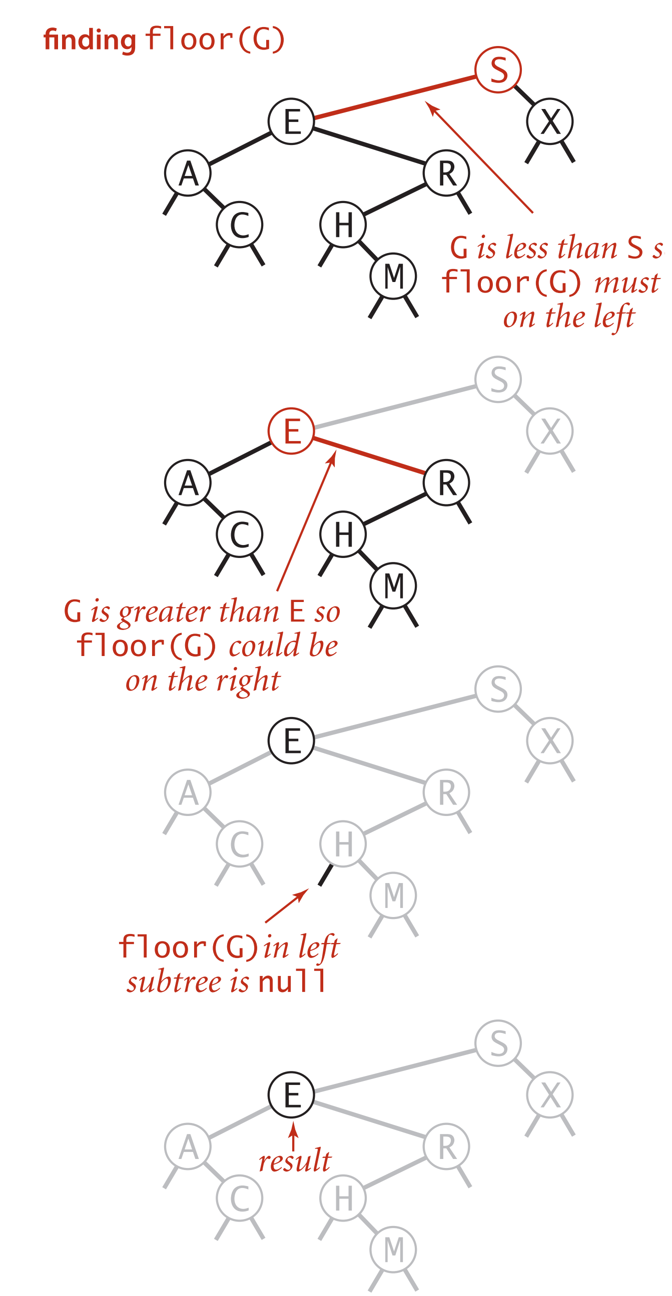
(if there is any key $\le k$ in right subtree);

otherwise it is the key in the root.



Computing the floor

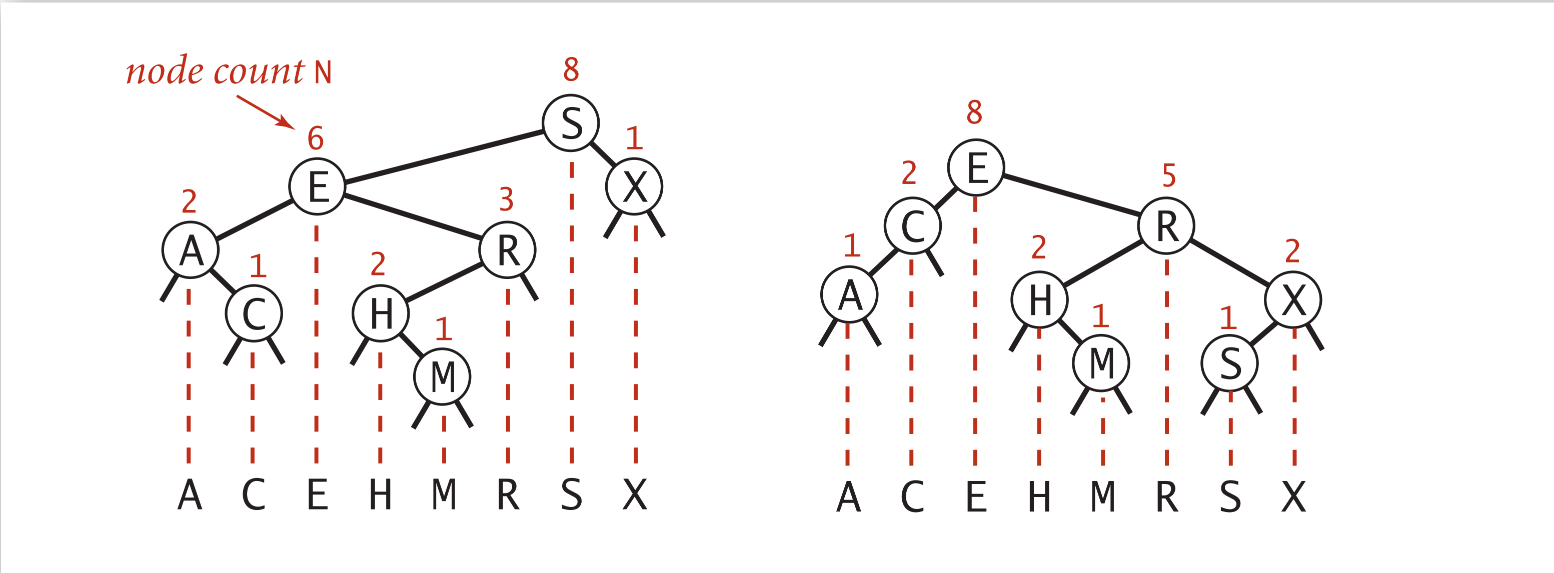
```
public Key floor(Key key)
{
   Node x = floor(root, key);
   if (x == null) return null;
   return x.key;
}
private Node floor(Node x, Key key)
{
   if (x == null) return null;
   int cmp = key.compareTo(x.key);

   if (cmp == 0) return x;

   if (cmp < 0)  return floor(x.left, key);

   Node t = floor(x.right, key);
   if (t != null) return t;
   else           return x;

}
```



Subtree counts

In each node, we store the number of nodes in the subtree rooted at that node.

To implement **`size()`**, return the count at the root.



Remark. This facilitates efficient implementation of **`rank()`** and **`select()`**.

BST implementation: subtree counts

```
private class Node
{
   private Key key;
   private Value val;
   private Node left;
   private Node right;
   private int N;
}
```

number of nodes in subtree

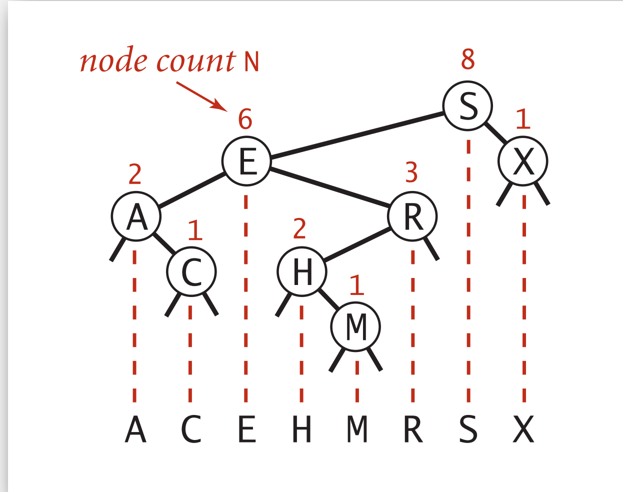
```
public int size()
{  return size(root);  }
```

```
private int size(Node x)
{
   if (x == null) return 0;
   return x.N;
}
```

```
private Node put(Node x, Key key, Value val)
{
   if (x == null) return new Node(key, val);
   int cmp = key.compareTo(x.key);
   if      (cmp  < 0) x.left  = put(x.left,  key, val);
   else if (cmp  > 0) x.right = put(x.right, key, val);
   else if (cmp == 0) x.val = val;
   x.N = 1 + size(x.left) + size(x.right);
   return x;
}
```

Rank

Rank. How many keys < k ?



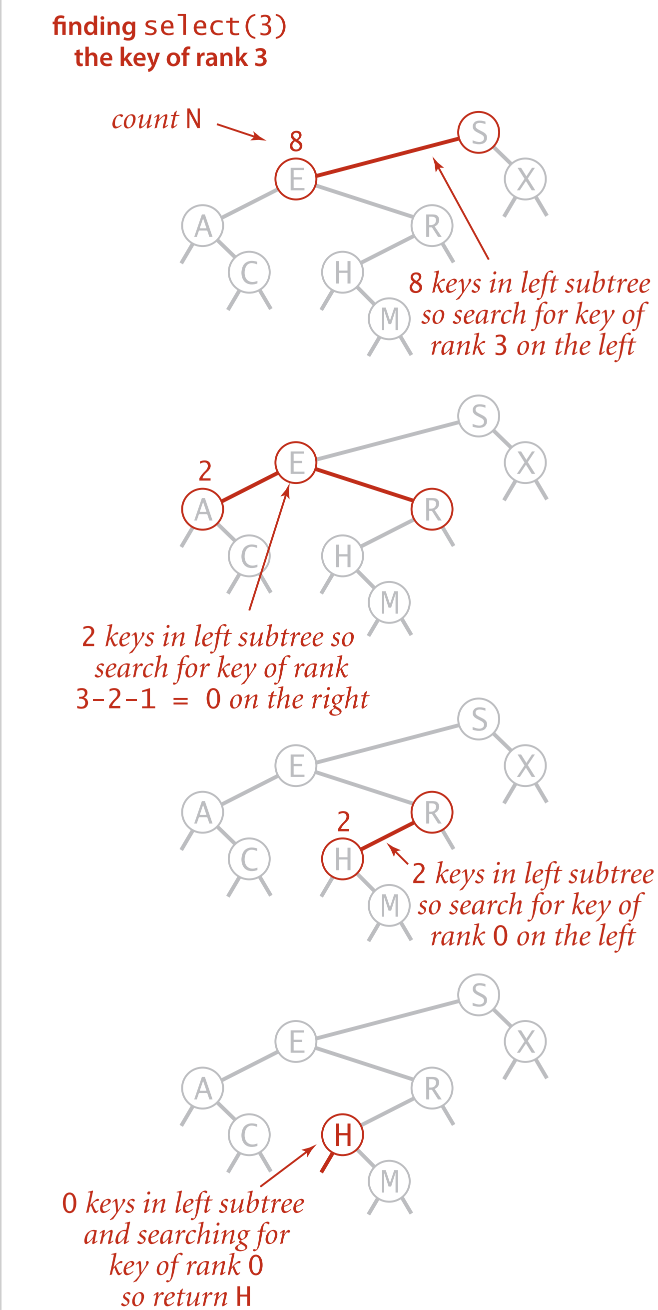
Easy recursive algorithm (4 cases!)

```
public int rank(Key key)
{  return rank(key, root);  }

private int rank(Key key, Node x)
{
   if (x == null) return 0;
   int cmp = key.compareTo(x.key);
   if      (cmp  < 0) return rank(key, x.left);
   else if (cmp  > 0) return 1 + size(x.left) + rank(key, x.right);
   else if (cmp == 0) return size(x.left);
}
```

Selection

Select. Key of given rank.

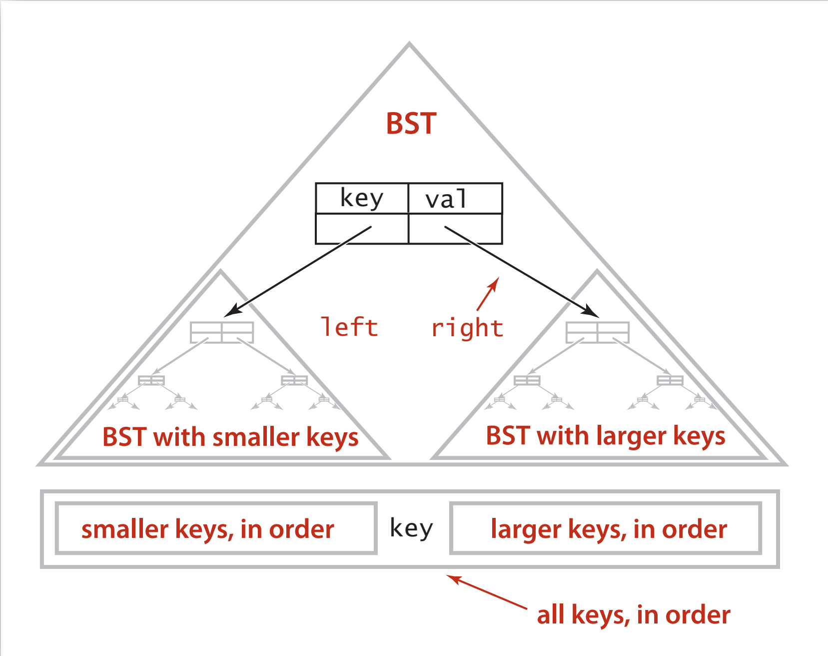
```
public Key select(int k)
{
    if (k < 0) return null;
    if (k >= size()) return null;
    Node x = select(root, k);
    return x.key;
}

private Node select(Node x, int k)
{
   if (x == null) return null;
   int t = size(x.left);
   if      (t  > k)
      return select(x.left,  k);
   else if (t  < k)
      return select(x.right, k-t-1);
   else if (t == k)
      return x;
}
```



Inorder traversal

- Traverse left subtree.
- Enqueue key.
- Traverse right subtree.

```
public Iterable<Key> keys()
{
    Queue<Key> q = new Queue<Key>();
    inorder(root, q);
    return q;
}

private void inorder(Node x, Queue<Key> q)
{
   if (x == null) return;
   inorder(x.left, q);
   q.enqueue(x.key);
   inorder(x.right, q);
}
```

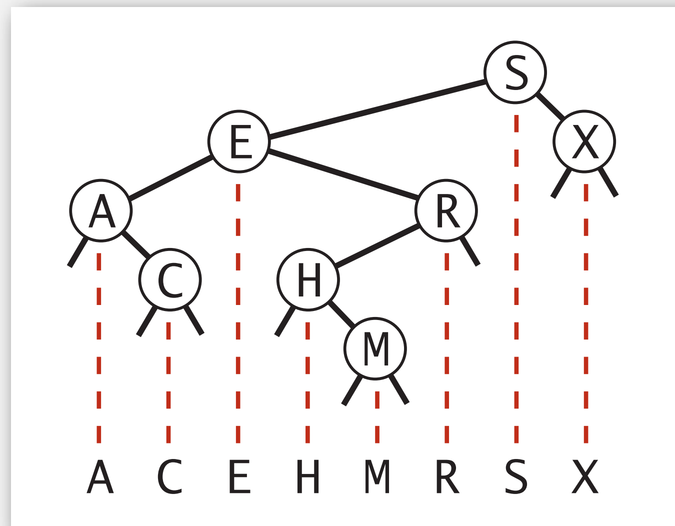


Property. Inorder traversal of a BST yields keys in ascending order.

Inorder traversal

- Traverse left subtree.
- Enqueue key.
- Traverse right subtree.

recursive calls	queue	function call stack
`inorder(S)`		S
`  inorder(E)`		S E
`    inorder(A)`		S E A
`      enqueue A`	A	
`      inorder(C)`		S E A C
`        enqueue C`	C	
`    enqueue E`	E	
`    inorder(R)`		S E R
`      inorder(H)`		S E R H
`        enqueue H`	H	
`        inorder(M)`		S E R H M
`          enqueue M`	M	
`      enqueue R`	R	
`  enqueue S`	S	
`  inorder(X)`		S X
`    enqueue X`	X	



BST: ordered symbol table operations summary

	sequential search	binary search	BST
search	N	lg N	h
insert	1	N	h
min / max	N	1	h
floor / ceiling	N	lg N	h
rank	N	lg N	h
select	N	1	h
ordered iteration	N log N	N	N

h = height of BST
(proportional to log N
if keys inserted in random order)

worst-case running time of ordered symbol table operations

- BSTs
- ordered operations
- **deletion**

ST implementations: summary

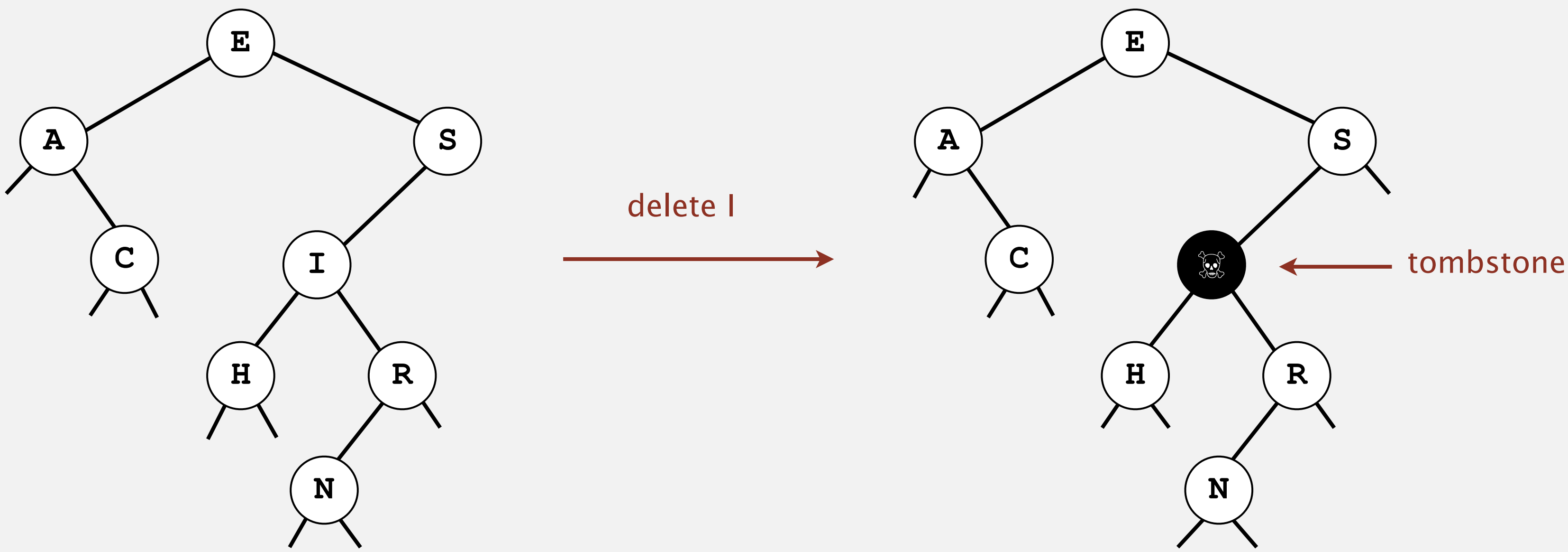
implementation	guarantee			average case			ordered iteration?	operations on keys
	search	insert	delete	search hit	insert	delete		
sequential search (linked list)	N	N	N	N/2	N	N/2	no	**`equals()`**
binary search (ordered array)	lg N	N	N	lg N	N/2	N/2	yes	**`compareTo()`**
BST	N	N	N	1.39 lg N	1.39 lg N	? ? ?	yes	**`compareTo()`**

Next. Deletion in BSTs.

BST deletion: lazy approach

To remove a node with a given key:

- Set its value to `null`.
- Leave key in tree to guide searches (but don't consider it equal to search key).



Cost. $\sim 2 \ln N'$ per insert, search, and delete (if keys in random order), where N' is the number of key-value pairs ever inserted in the BST.

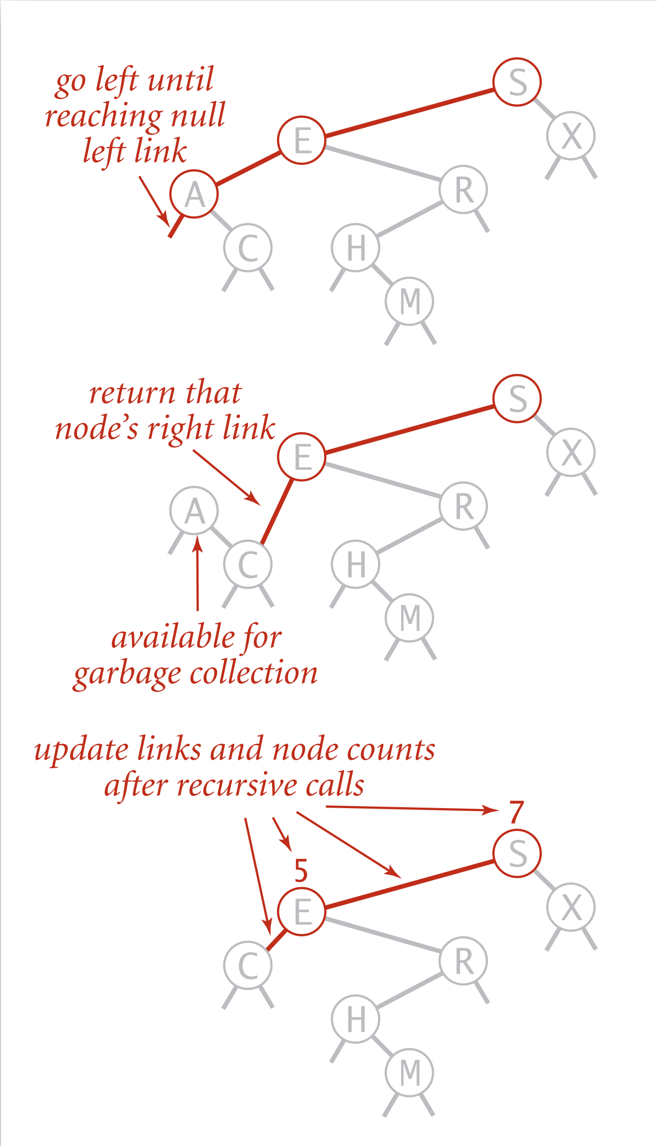
Unsatisfactory solution. Tombstone overload.

Deleting the minimum

To delete the minimum key:

- Go left until finding a node with a null left link.
- Replace that node by its right link.
- Update subtree counts.

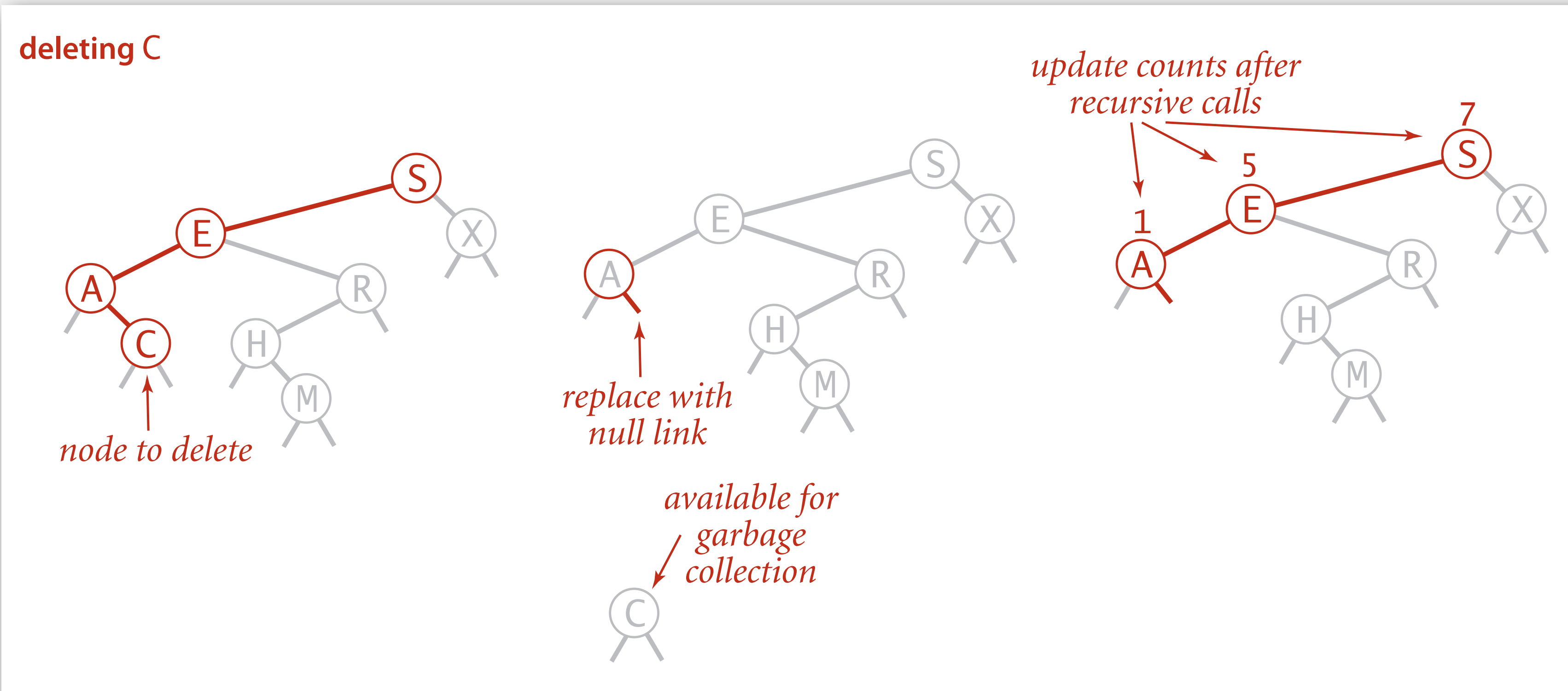
```
public void deleteMin()
{  root = deleteMin(root);  }

private Node deleteMin(Node x)
{
   if (x.left == null) return x.right;
   x.left = deleteMin(x.left);
   x.N = 1 + size(x.left) + size(x.right);
   return x;
}
```



Hibbard deletion

To delete a node with key k: search for node t containing key k.

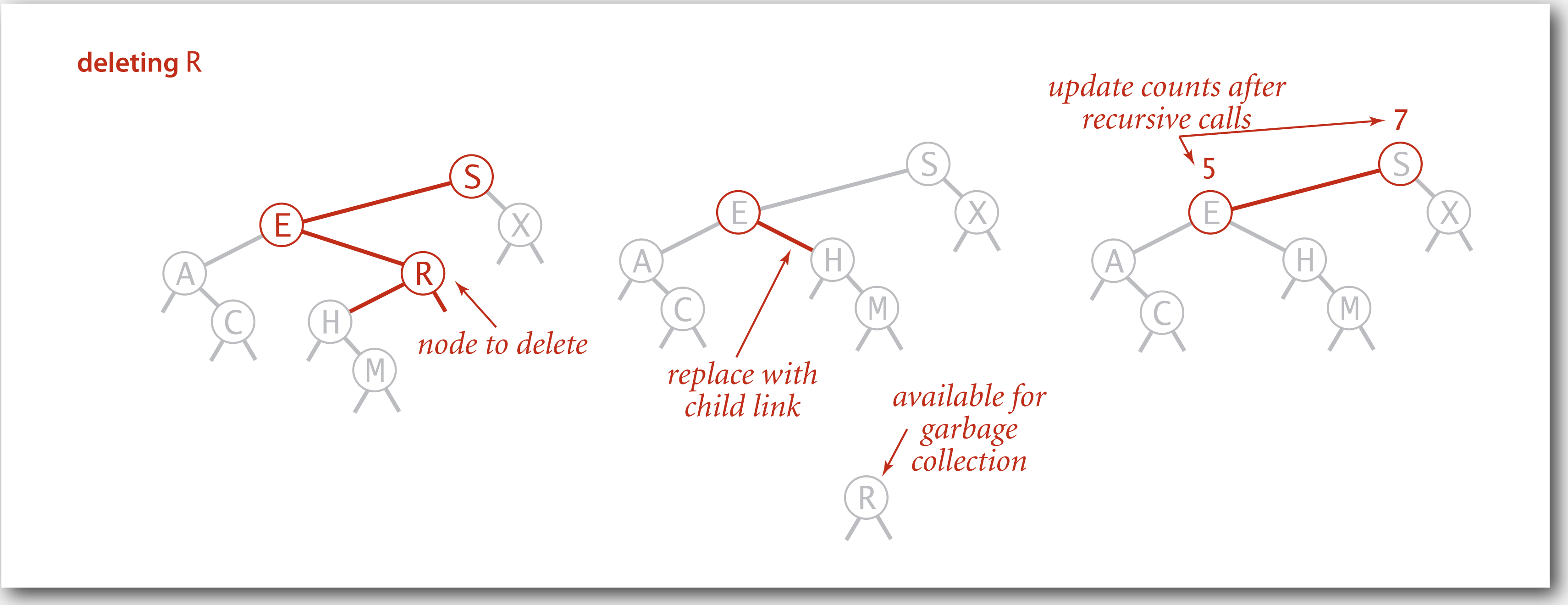
Case 0. [0 children] Delete t by setting parent link to null.



Hibbard deletion

To delete a node with key k: search for node t containing key k.

Case 1. [1 child] Delete t by replacing parent link.

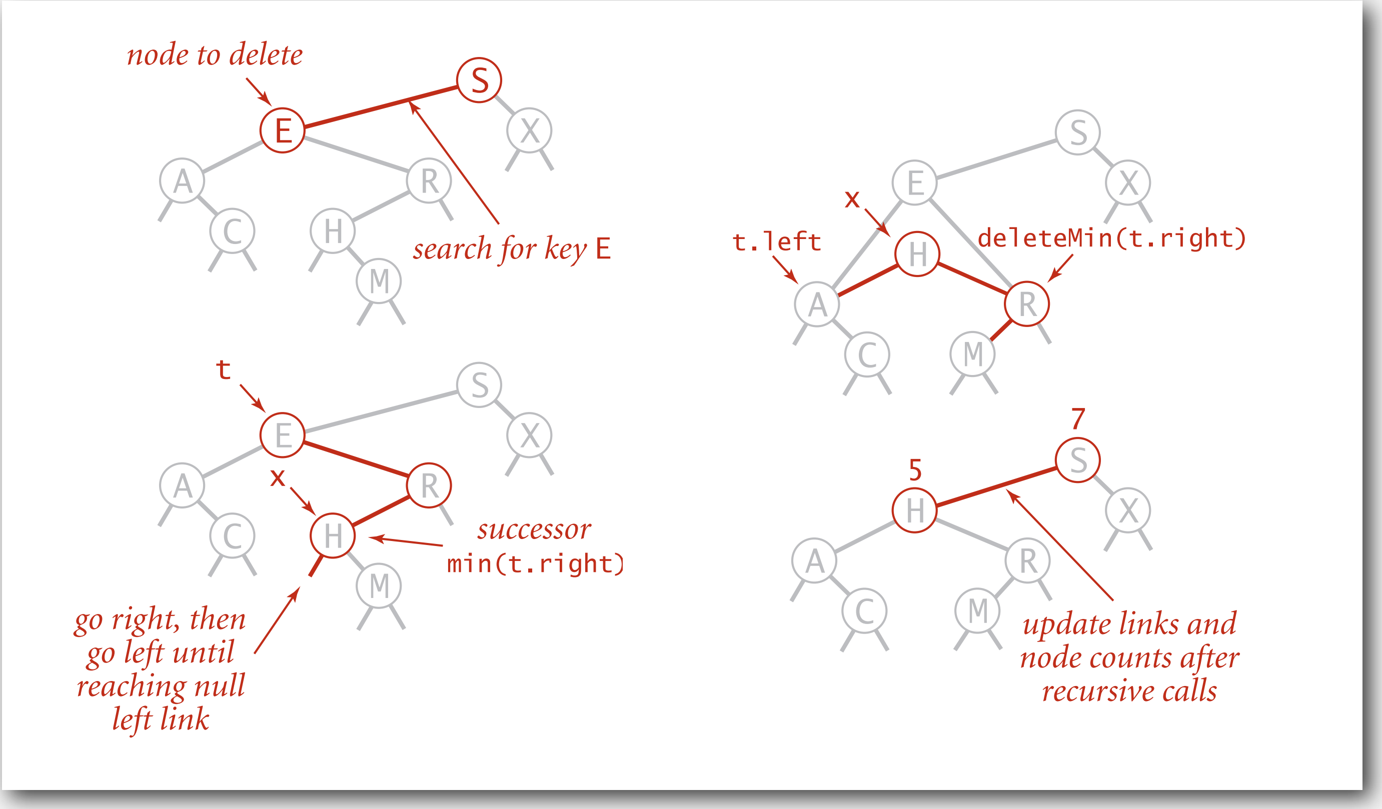


Hibbard deletion

To delete a node with key k: search for node t containing key k.

Case 2. [2 children]

- Find successor x of t. ← x has no left child
- Delete the minimum in t's right subtree. ← but don't garbage collect x
- Put x in t's spot. ← still a BST



Hibbard deletion: Java implementation

```
public void delete(Key key)
{  root = delete(root, key);  }

private Node delete(Node x, Key key) {
   if (x == null) return null;
   int cmp = key.compareTo(x.key);
   if      (cmp < 0) x.left  = delete(x.left,  key);
   else if (cmp > 0) x.right = delete(x.right, key);
   else {
      if (x.right == null) return x.left;

      Node t = x;
      x = min(t.right);
      x.right = deleteMin(t.right);
      x.left = t.left;
   }
   x.N = size(x.left) + size(x.right) + 1;
   return x;
}
```

search for key

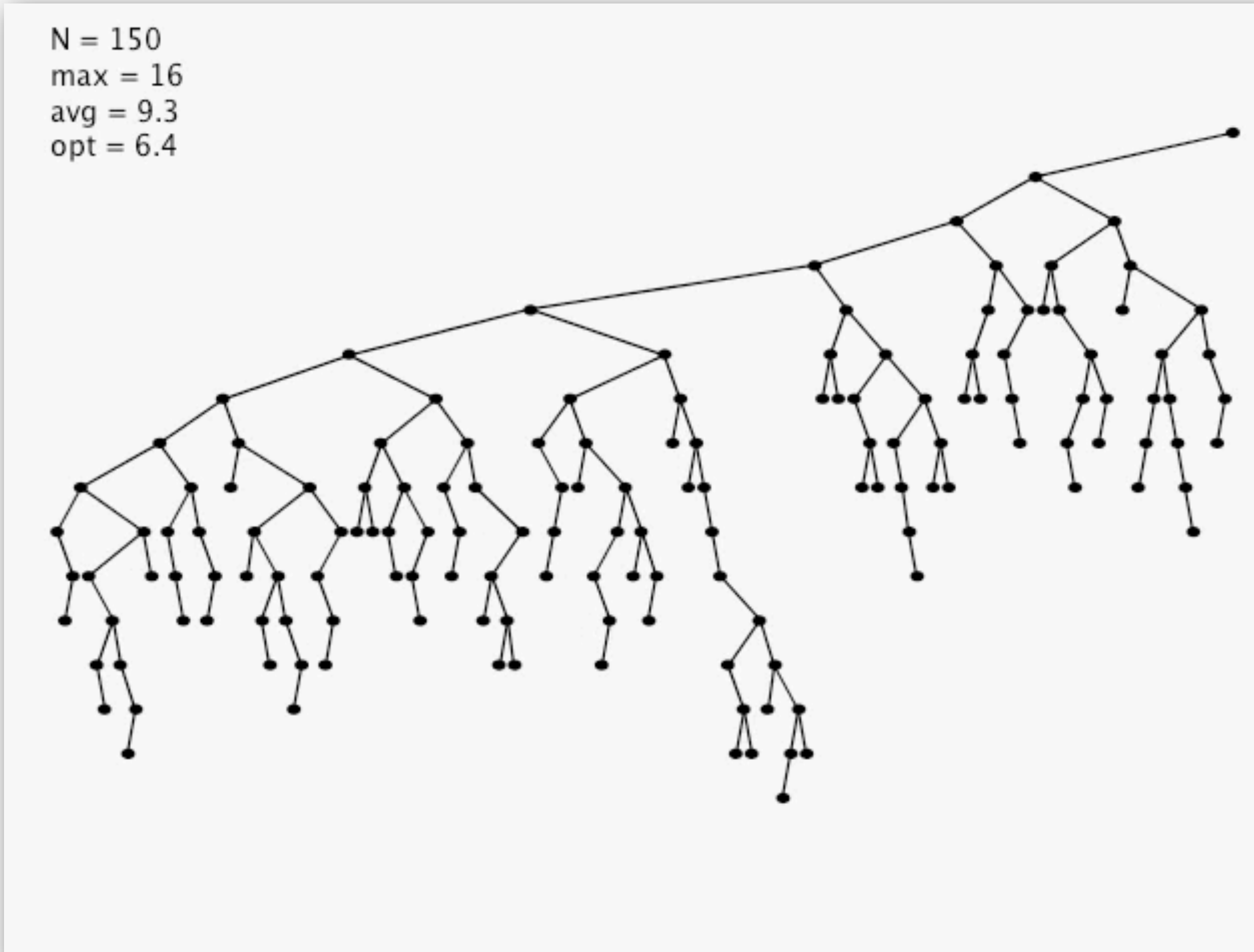
no right child

replace with successor

update subtree counts

Hibbard deletion: analysis

Unsatisfactory solution. Not symmetric.



Surprising consequence. Trees not random (!) $\Rightarrow$ $\mathrm{sqrt}\,(N)$ per op.

Longstanding open problem. Simple and efficient delete for BSTs.

ST implementations: summary

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	search	insert	delete	search hit	insert	delete		
sequential search (linked list)	N	N	N	N/2	N	N/2	no	`equals()`
binary search (ordered array)	lg N	N	N	lg N	N/2	N/2	yes	`compareTo()`
BST	N	N	N	1.39 lg N	1.39 lg N	$\sqrt{N}$	yes	`compareTo()`

other operations also become $\sqrt{N}$
if deletions allowed

Next lecture. Guarantee logarithmic performance for all operations.