#### CIKM'12

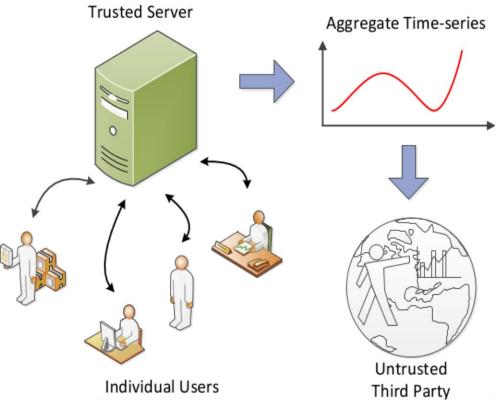
# Real-Time Aggregate Monitoring under Differential Privacy

Liyue Fan, Li Xiong Department of Math & Computer Science Emory University



# Real-Time Aggregate

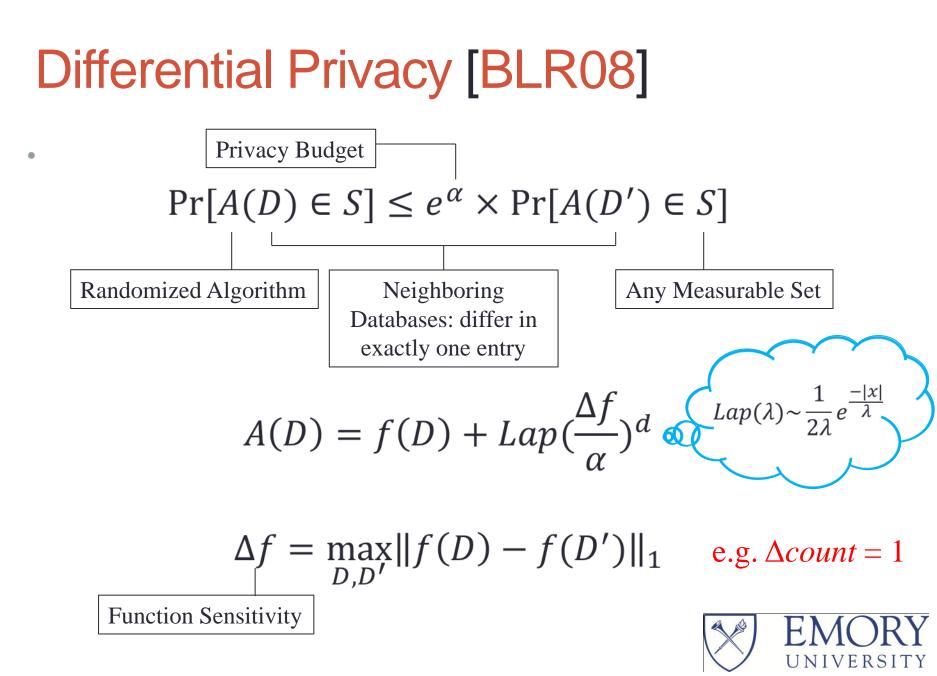
- Disease Surveillance
  - E.g. daily count of flu cases at a hospital
- Traffic Monitoring
  - E.g. hourly count of vehicles at a highway junction



#### Goal:

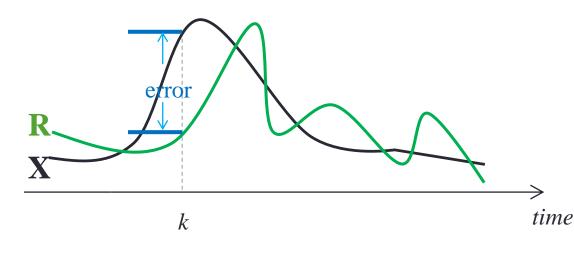
Strong Privacy, High Utility





### Problem Statement

- A univariate, discrete *Time-Series*  $\mathbf{X} = \{x_k\}$  with  $0 \le k < T$
- **Problem**: Given time series **X** and differential privacy budget α, release α-differentially private series **R** with high utility.
- Utility: relative error





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# Challenges

- High sensitivity T
- **Low** utility  $Lap(T/\alpha)$
- Real-time requirement

### • Existing methods:

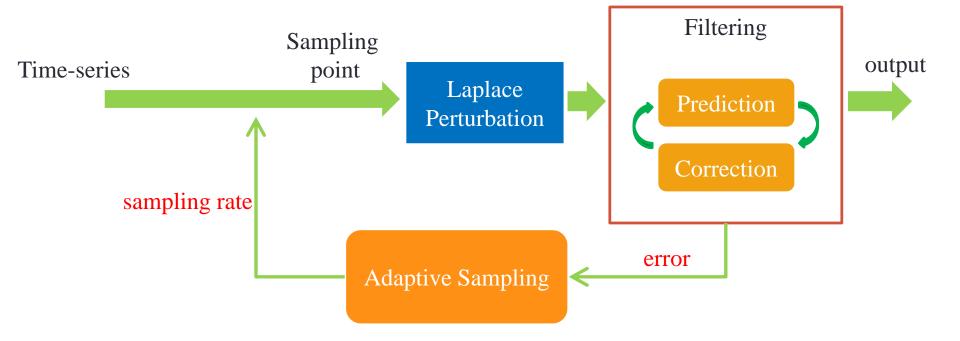
- Baseline LPA
  - Applies Laplace perturbation at every time stamp
  - Low Utility
- State-of-the-art DFT
  - Performs Discrete Fourier Transform to the raw aggregate series
  - Reduced sensitivity, <u>not applicable</u> to real-time applications





- Sampling
- Model-based Estimation
- Feedback

### FAST: a real-time system with <u>Filtering and Adaptive</u> <u>Sampling for monitoring aggregate Time-series</u>





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### Filtering

Process Model

$$x_{k+1} = x_k + \omega$$
  
 
$$\omega \sim \mathbb{N}(0, Q) \qquad \text{Process noise}$$

Measurement Model

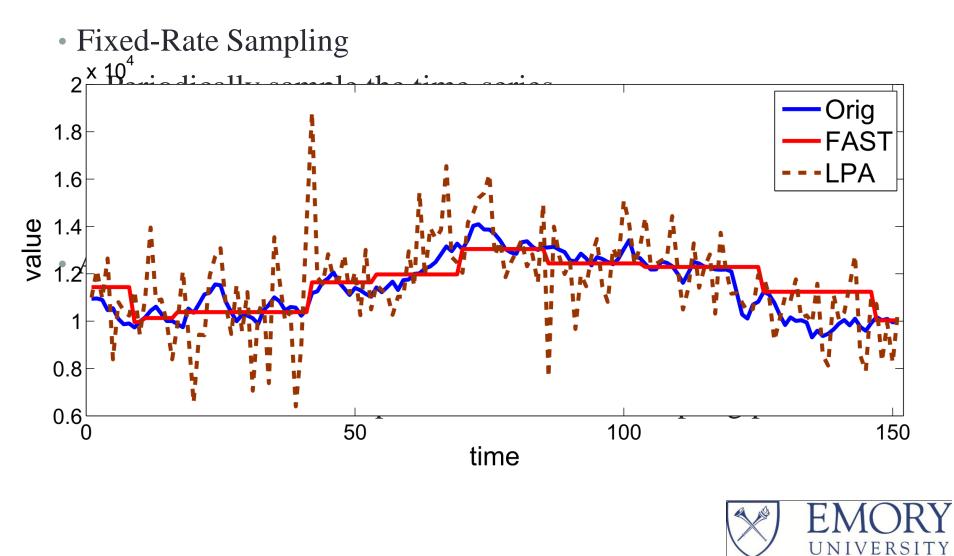
$$z_k = x_k + \nu$$
  

$$\nu \sim Lap(\lambda)$$
 Measurement noise

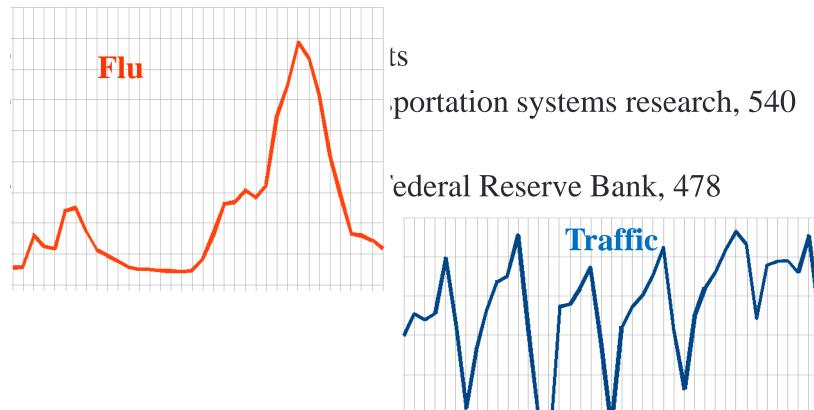
- Approximate measurement noise with Gaussian  $\nu \sim \mathbb{N}(0, R)$
- $\rightarrow$  the Kalman filter



### Sampling

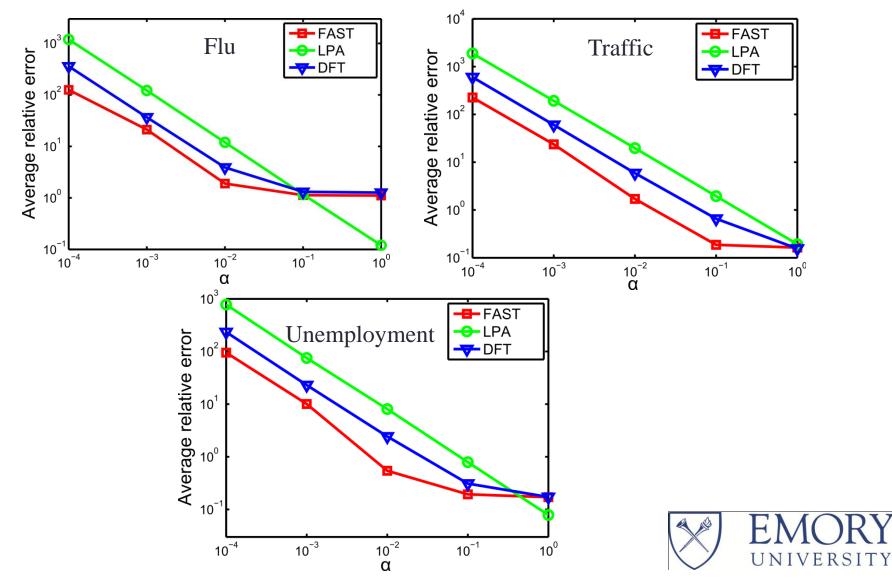


### **Evaluation: Data Sets**









# Conclusion

#### Contributions:

- Establish the state-space model for real-time aggregate under differential privacy
- Adaptively sample the data series to reduce perturbation noise
- Dynamically adjust the sampling rate and estimation based on feedback
- Demonstrate the superior performance of FAST with real-world data sets

#### On-going Work:

- Accurate posterior estimation
- Extension to sharing spatio-temporal data sets

#### Questions?

- Contact: <u>liyue.fan@emory.edu</u>
- AIMS Group: <u>www.mathcs.emory.edu/aims</u>

