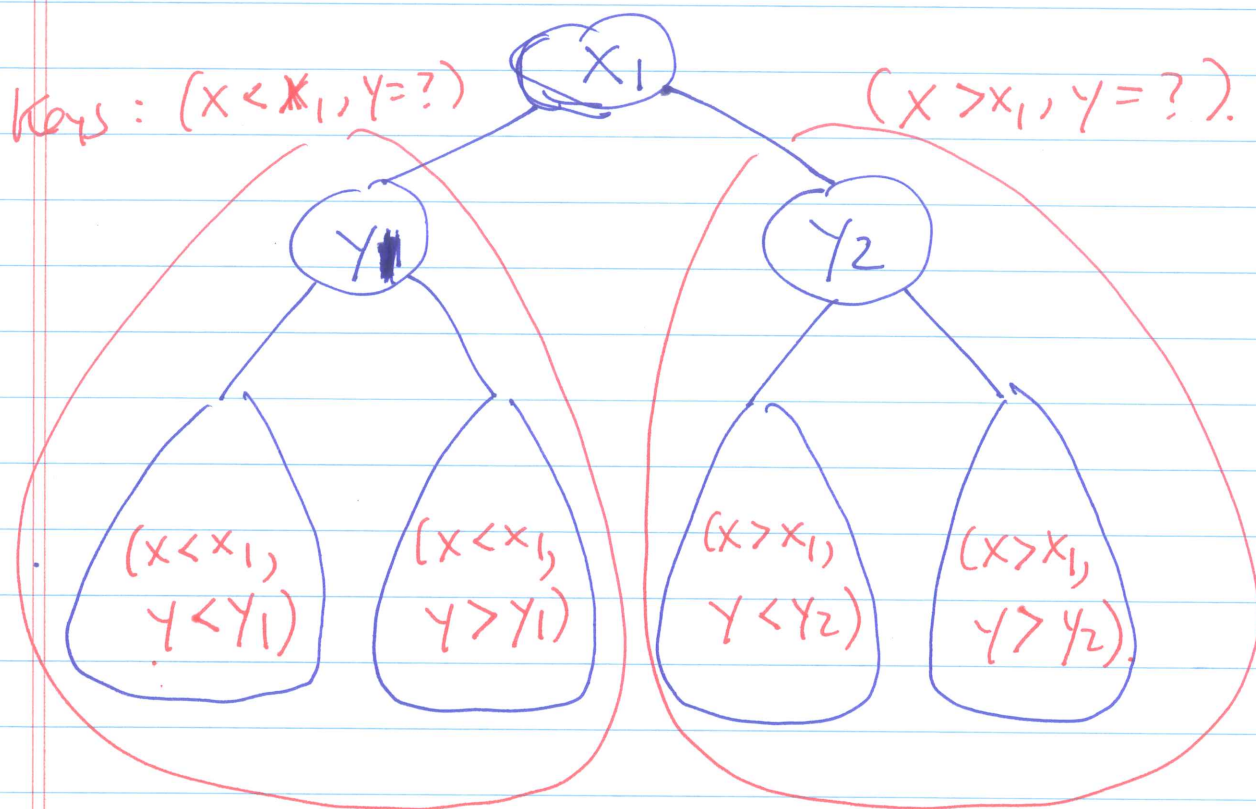


Multi-dim Indexes (tree)

⑧

- Kd-tree: eg: 2 dimension. (x, y) .



Note: In the classical kd-tree =

data points (multi-dim. values) are placed at the nodes of the kd-tree.

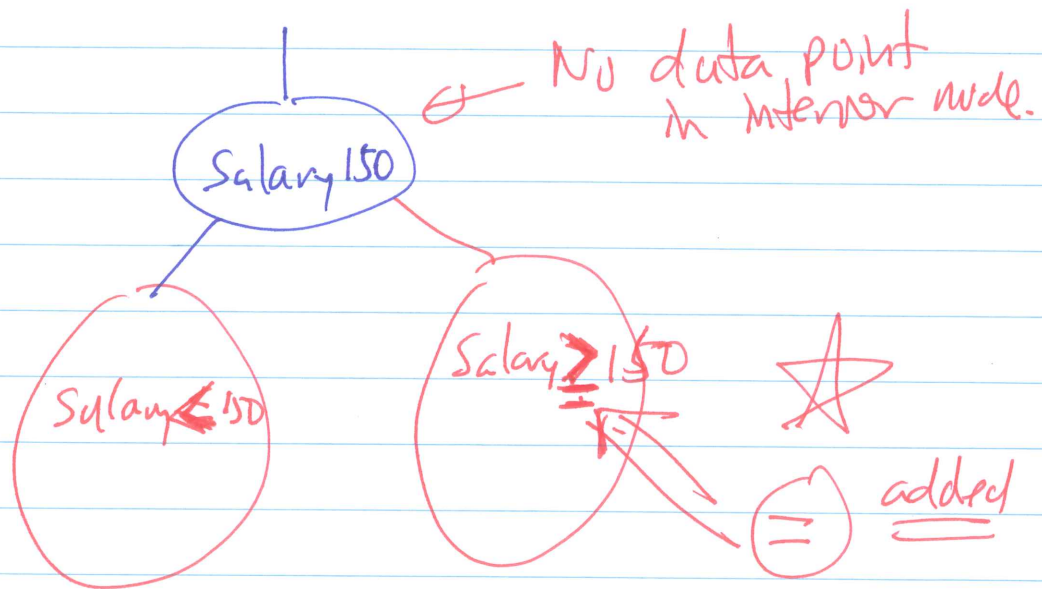
Modifications needed to ~~so~~ simplify storing kd-tree on disk.

Modifications to classical kd-tree:

(1) Interior nodes do NOT store data.

Interior nodes store:

- (A) attribute (name)
- (B) dividing value.



(2) Only the leaf blocks (nodes) contains data.

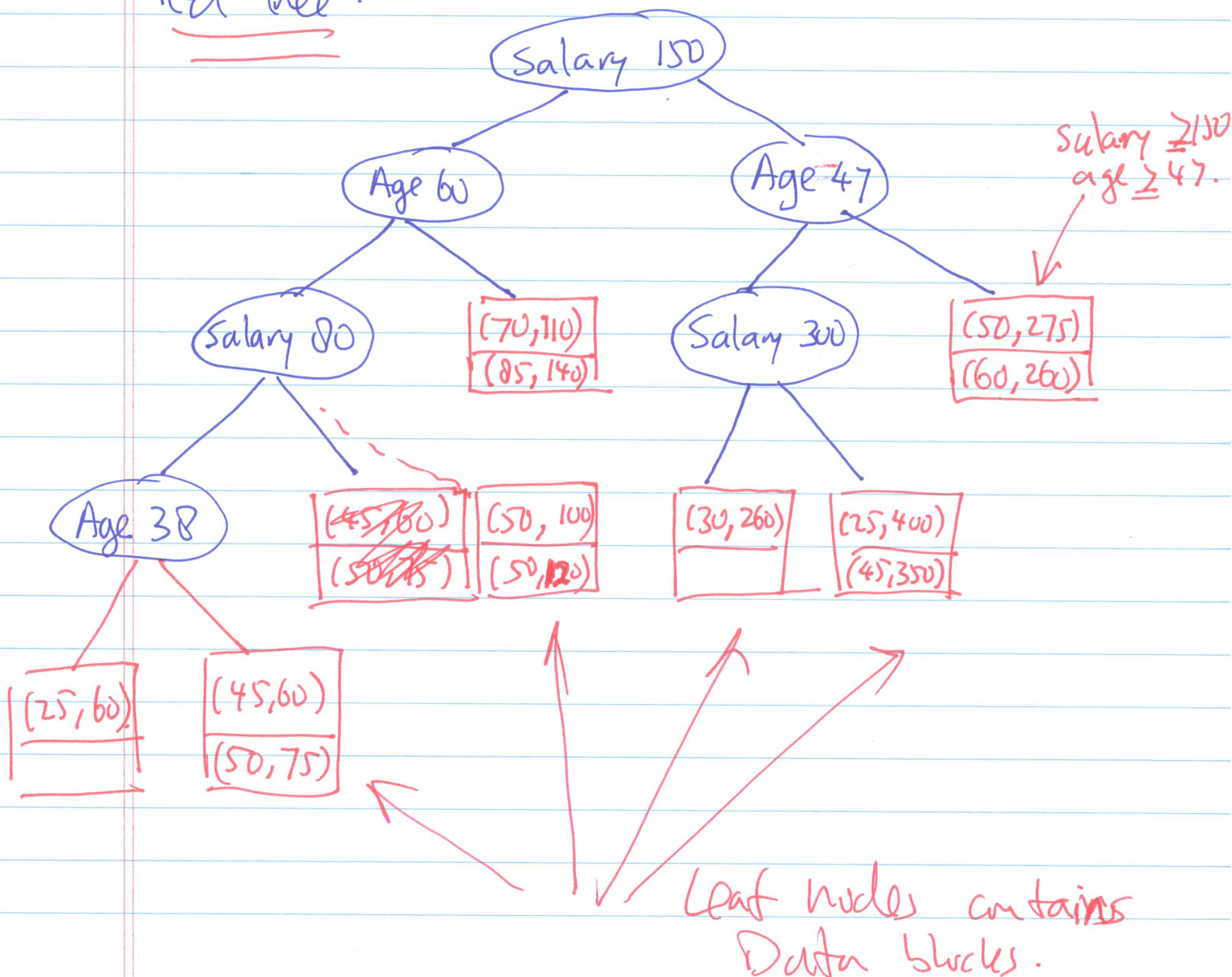
Example:

Input data:

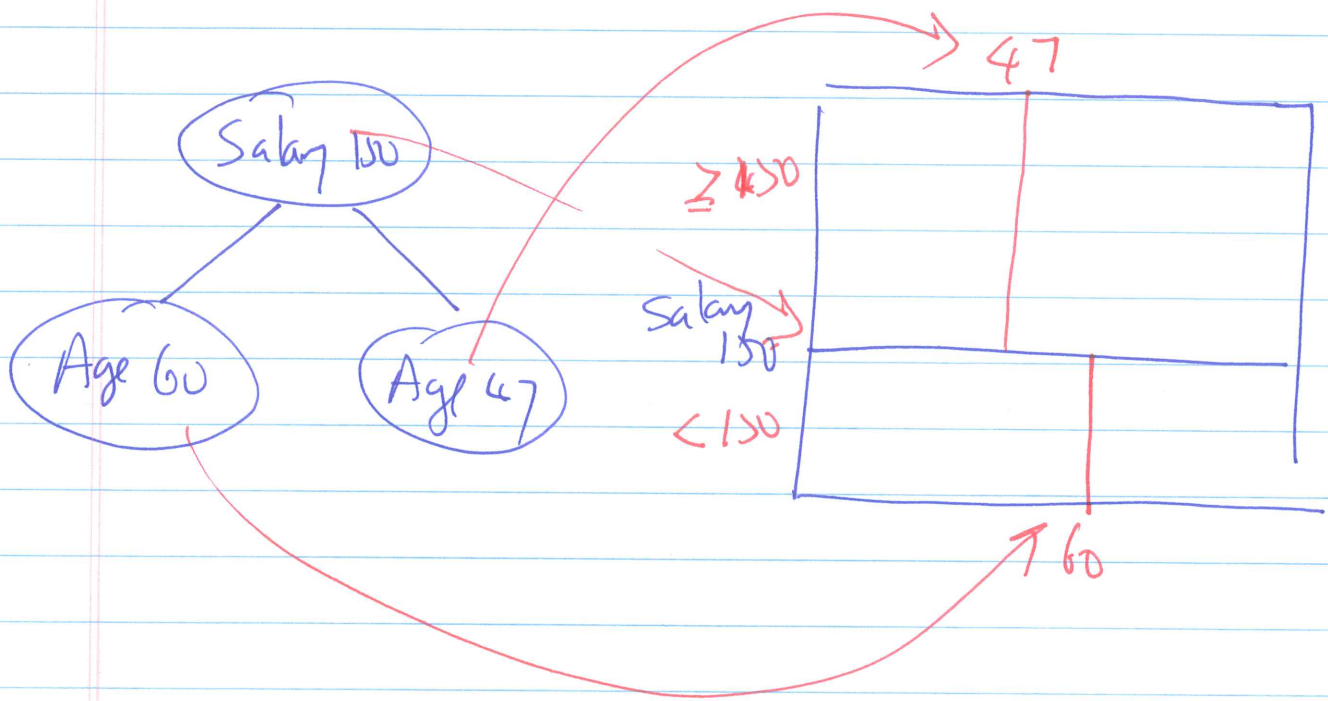
(25, 60) (45, 60) (50, 75) (50, 100)
(50, 120) (70, 110) (85, 140) (30, 260)
(25, 400) (43, 350) (50, 275) (60, 260)

Age Salary

Kd-tree:

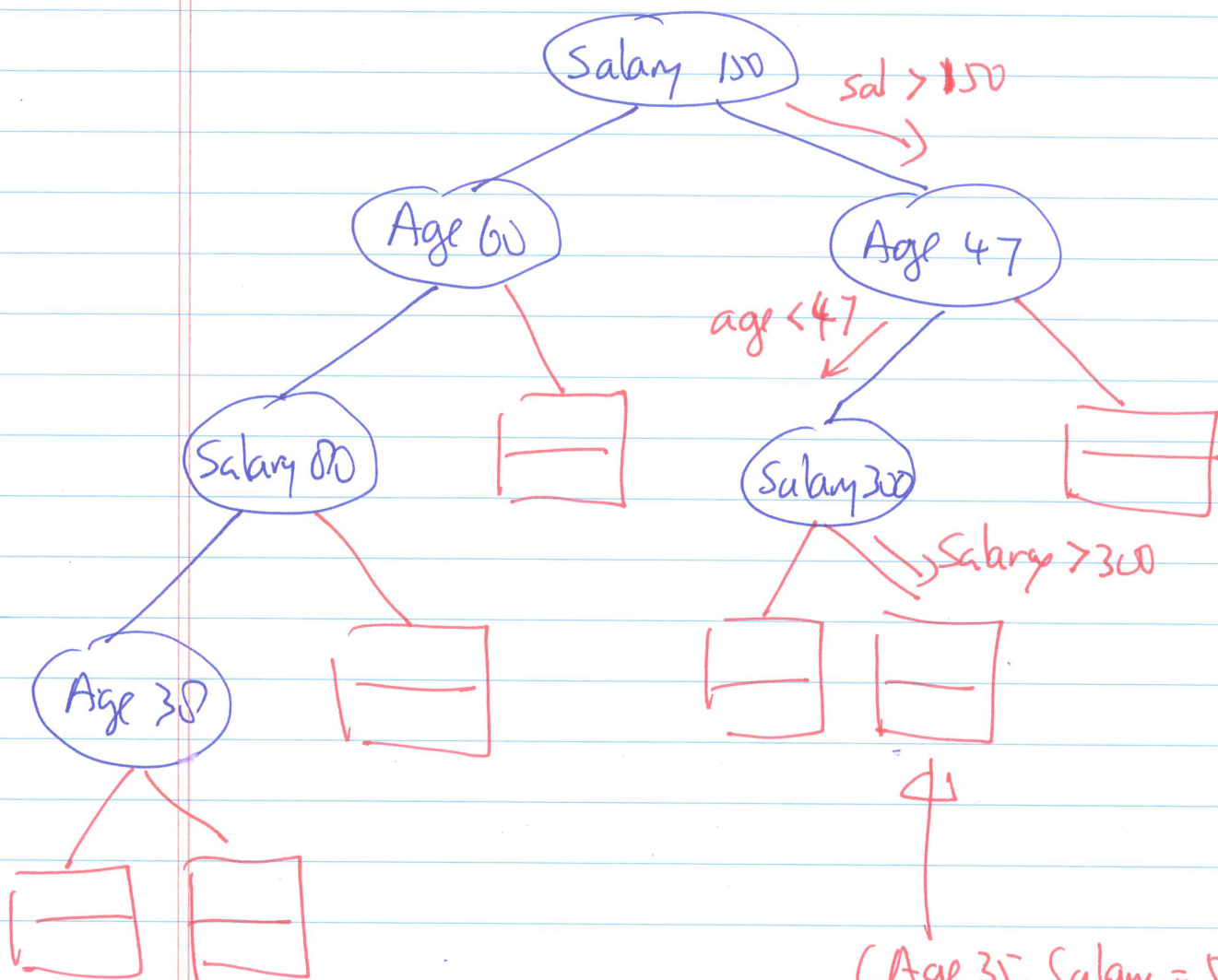


Pictorial Representation of a 2-dim kd tree:



Lookup in a kd-tree:

Lookup: (Age = 35, Salary = 500k)



(Age 35, Salary = 500k)

must be store HERE

(search in block)

Insert into a kd-tree.

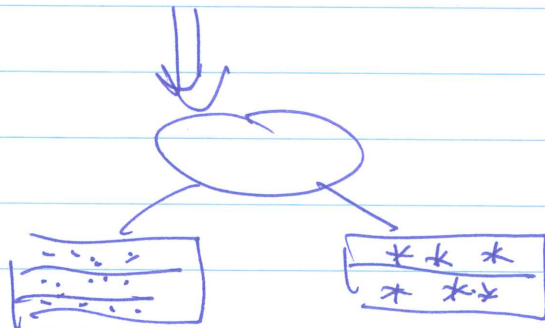
(1) do a lookup first - to find the leaf blk

(2) If leaf block has room for record

→ Insert in block.

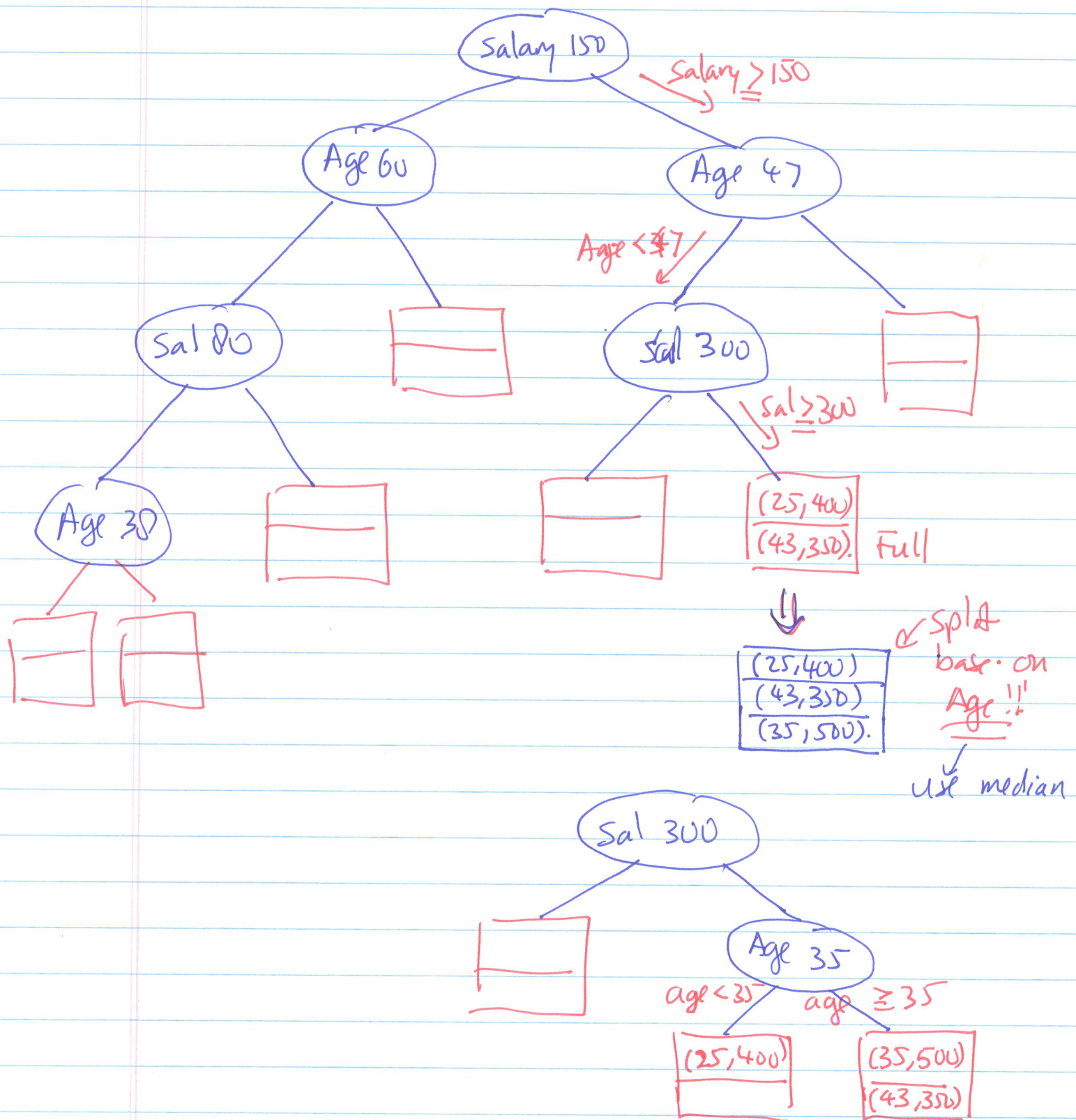
If leaf block is full

→ Split block. (make an
interior node).



the dimension of
the attribute used
to split depends
on the level of
the leaf block !!!

Example: insert (Age=35, salary=500k)



Delete operation

- Delete is very complicated. (especially takes many blocks accesses.)
- So instead of Delete,

Database systems usually

Rebuilds the indexes

from scratch.

- take down the database at night.
- Rebuild index files.

Kd-trees. performance

• Partial Match query:

(1) for the dimension that has a
given search value

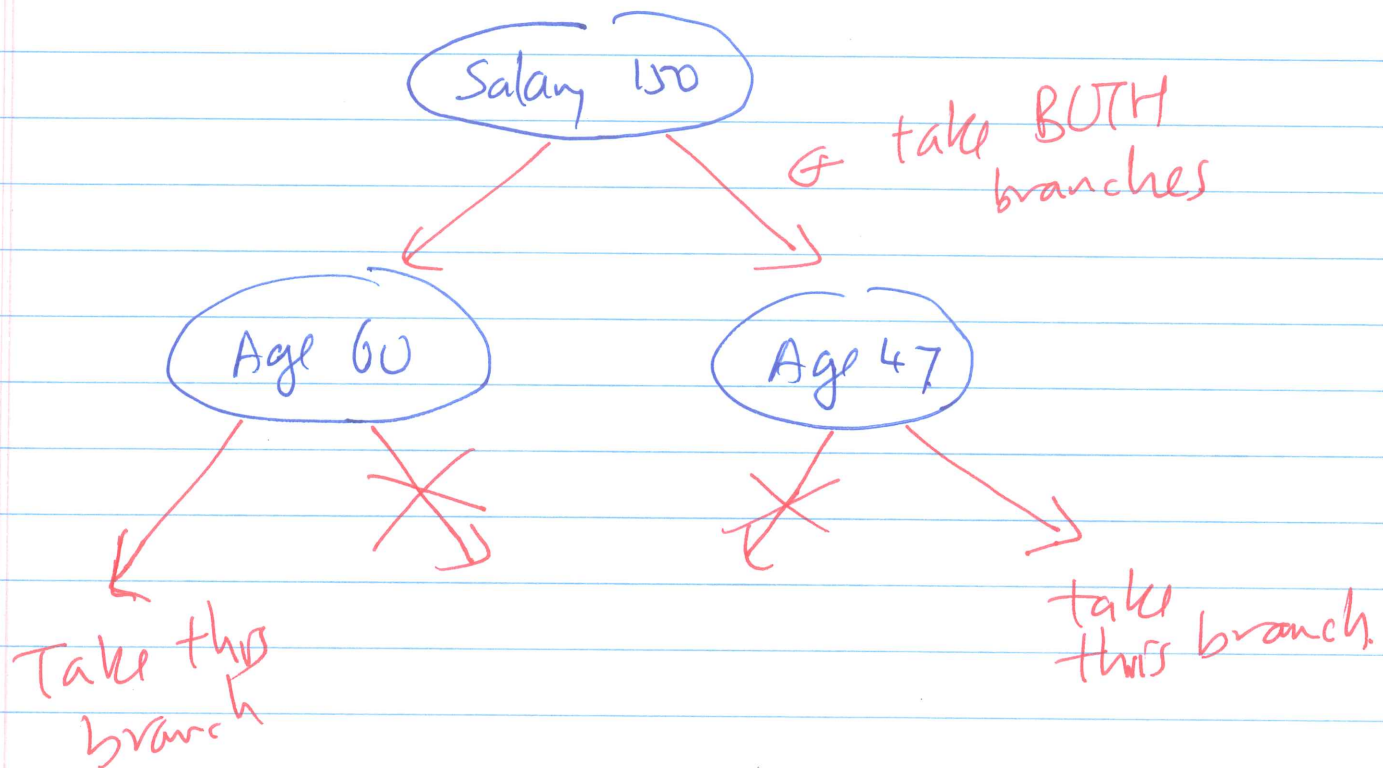
↓
take the (one) ^{correct} branch down.

(2) for the dimension that has

NO search value

↓
take BOTH branches down.

Example: (age = 50, salary = *)



And so on.

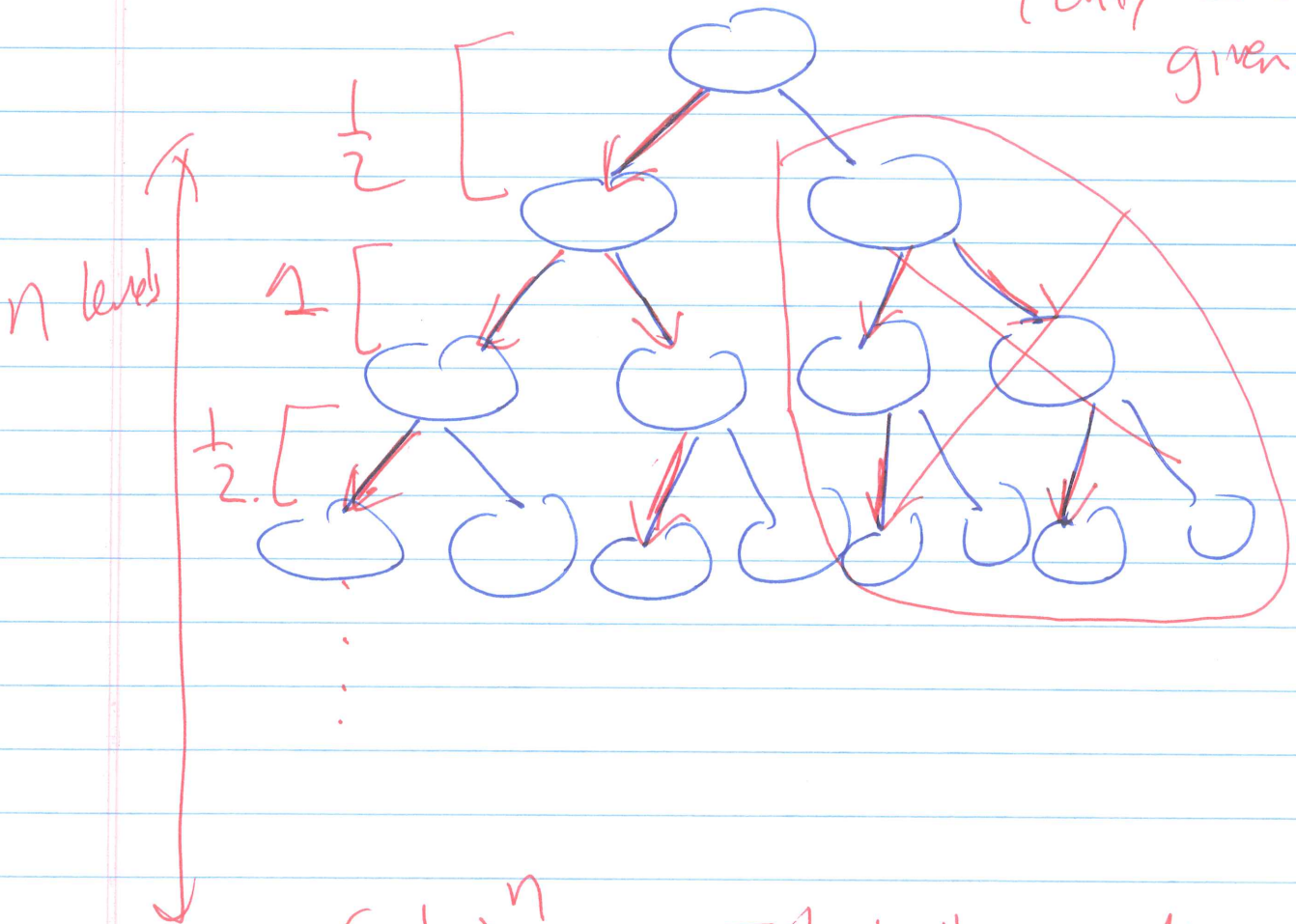
Question: How much did this improve?

How much did the kd-tree reduce the search space ???

Assume: kd-tree is balanced
(same # height every where)

$2n$ levels.

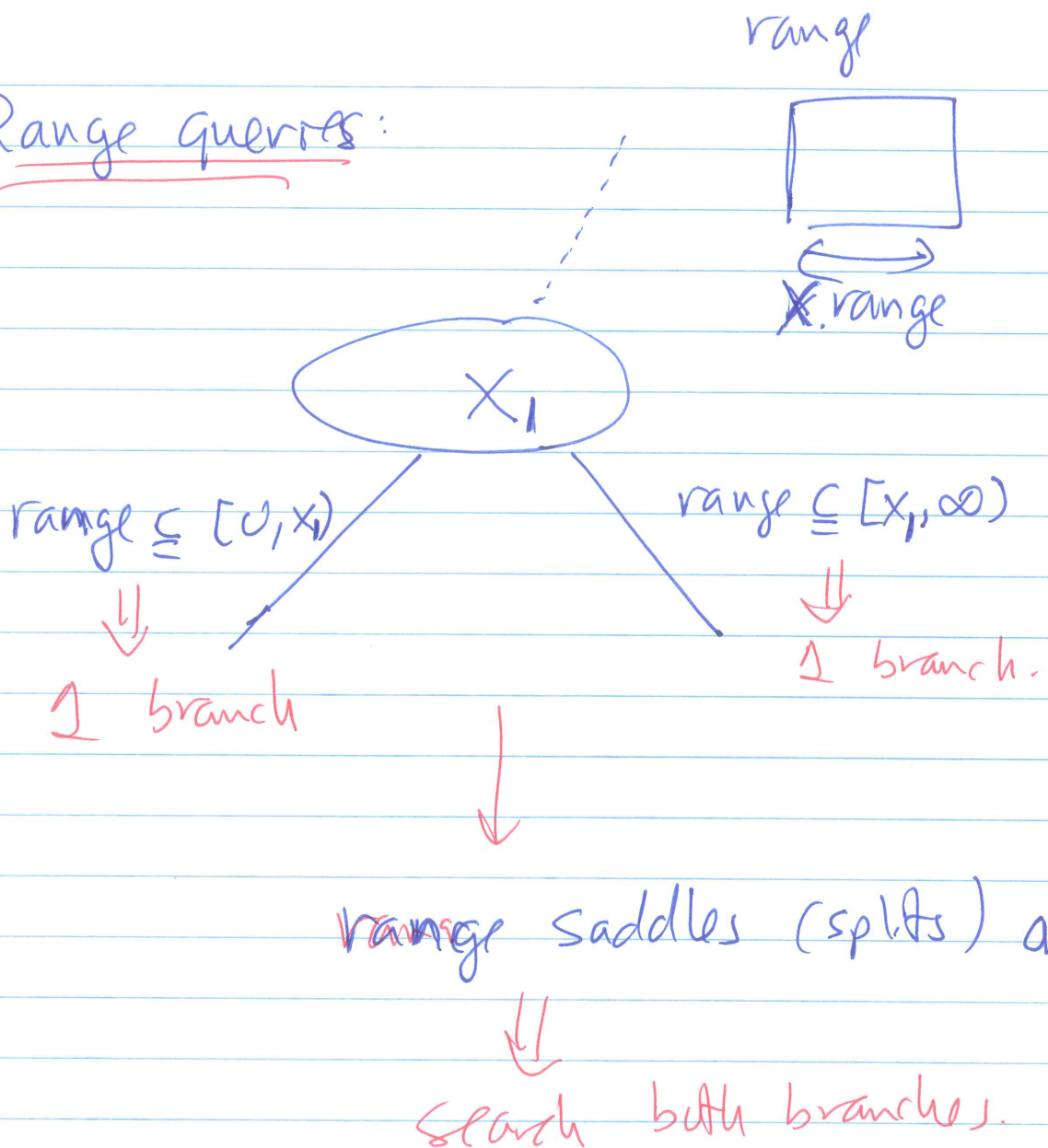
(only 1 dim given)



$$\underline{\underline{\left(\frac{1}{2}\right)^n \times \text{Total \# records}}}$$

(pretty good)

* Range queries:



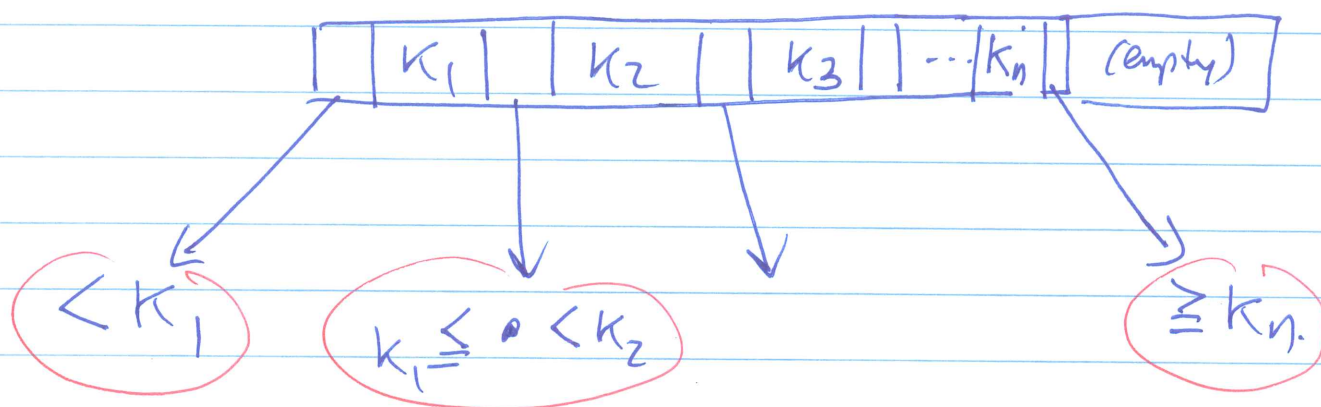
(same decision in the second dimension)

• Nearest Neighbor: ~~no use at all~~....

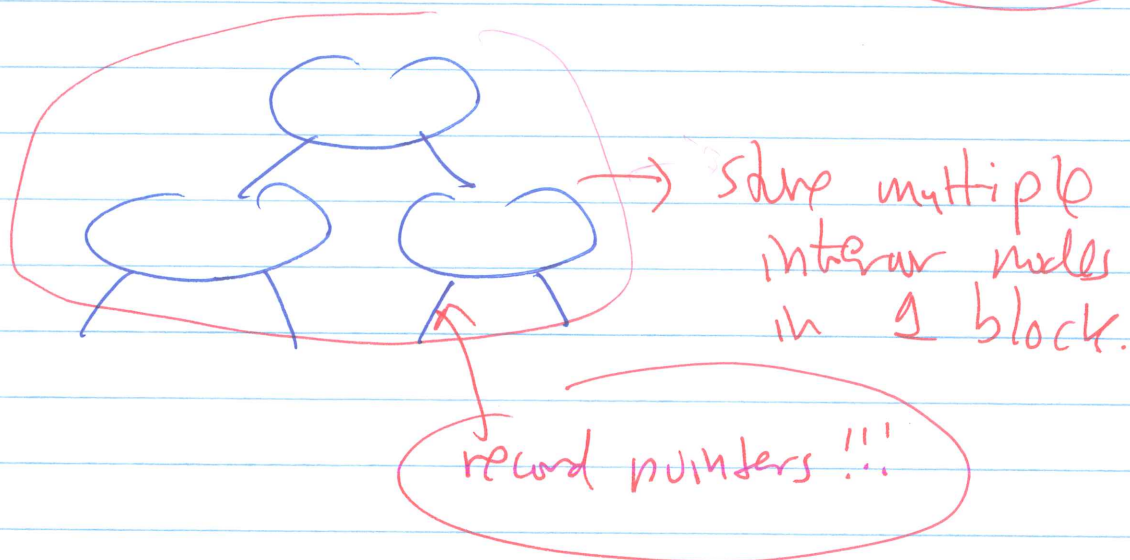
tough (not discussed)
in book

Adapting kd-tree to Secondary storage

- (1) Use multi-way branches at interior nodes. (like a B-tree.)



- (2) Group interior nodes into one block



The pointers uses are

reward pointers.

Use pointer swizzling when

the block is read into memory !!